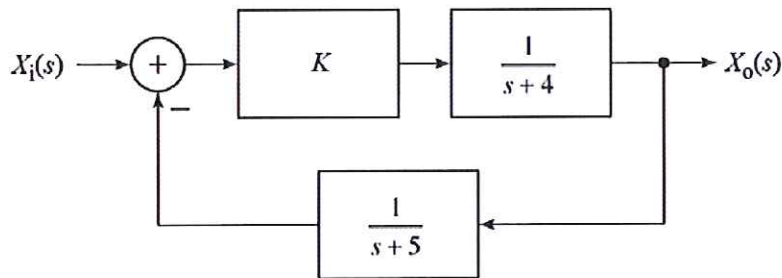


Ex:



- a) Find the transfer function, $H(s) = \frac{X_o(s)}{X_i(s)}$, for the above system.
- b) For what values of K is the system stable? (Consider positive and negative values of K .)

sol'n: a) The forward path is $K \left(\frac{1}{s+4} \right) = A(s)$, and the feedback path is $\frac{1}{s+5} = B(s)$. Using the formula for the transfer function of a standard feedback system yields the following expression:

$$H(s) = \frac{A(s)}{1 + A(s)B(s)} = \frac{K/(s+4)}{1 + \frac{K}{s+4} \cdot \frac{1}{s+5}}$$

- b) The first step in determining stability is to write $H(s)$ as a ratio of polynomials in s .

$$H(s) = \frac{\frac{K}{s+4}}{1 + \frac{K}{s+4} \cdot \frac{1}{s+5}} = \frac{K(s+5)}{(s+4)(s+5) + K}$$

The system is stable when the roots of the denominator have non-positive real parts.

$$(s+4)(s+5) + K = 0$$

or

$$s^2 + 9s + 20 + K = 0$$

The quadratic equation gives the values of the roots.

$$s = -\frac{9}{2} \pm \sqrt{\left(\frac{9}{2}\right)^2 - (20+K)}$$

For the real part of s to be positive, the square root would have to be greater than $+9/2 = +4.5$. The extremum value of K before the system becomes unstable occurs when the square roots equals 4.5.

$$\sqrt{\left(\frac{9}{2}\right)^2 - (20+K)} = 4.5$$

or

$$\left(\frac{9}{2}\right)^2 - (20+K) = 4.5^2$$

$$\text{or } -(20+K) = 0$$

$$\text{or } K = -20$$

The system is stable for $K \geq -20$