

EX: Consider a brush DC motor described by the following equations:

$$0 = v - Ri - K\omega$$

$$J \frac{d\omega}{dt} = Ki - C$$

$$\frac{d\theta}{dt} = \omega$$

The parameters for the motor are as follows:

$$L = 0 \text{ H (the motor has no inductance)}$$

$$R = 2 \Omega$$

$$K = 4 \text{ Nm/A}$$

$$J = 0.8 \text{ kg m}^2$$

$$C = 8 \text{ Nm}$$

The voltage applied to the motor is constant at 12 V for a very long time before time $t = 0$. Thus, the motor is running at constant velocity just before $t = 0$.

At $t = 0$, the voltage applied to the motor drops instantly to 0 V and stays at 0 V from then on.

- Calculate the value of $\omega(t = 0^-)$. Note that this is just before time $t = 0$.
- Calculate the value of the power, $p_J(t = 0^+)$, arising from the moment of inertia of the motor and its changing velocity immediately after time $t = 0$. Note that this is just after time $t = 0$.

sol'n: a) At $t=0^-$, the motor is in steady-state.

Thus, $\frac{dw}{dt} = 0$, (constant velocity).

$$\therefore 0 = Ki - C \quad \text{and} \quad i = \frac{C}{K}$$

Substituting into 1st eq'n, we have

$$0 = v - Ri - Kw \quad \text{where} \quad i = \frac{C}{K}$$

$$\text{After some algebra, } \omega = \frac{v - Rc/K}{K}$$

$$\text{or } \omega = \frac{12V - 2\Omega \cdot 8Nm / 4 Nm/A}{4 Nm/A \text{ or } 4Vs}$$

$$\omega = 2 \text{ r/s}$$

b) Power from changing velocity of motor is

$$P_J(t=0^+) = J \omega \Big|_{t=0^+} \cdot \frac{d\omega}{dt} \Big|_{t=0^+}$$

We know the speed of the motor will not change instantly. Thus, $\omega(t=0^+) = \omega(t=0^-)$, and $\omega(t=0^-) = 2 \text{ r/s}$ from (a).

$$\text{From the 2nd motor eq'n, } J \frac{d\omega}{dt} \Big|_{t=0^+} = Ki \Big|_{t=0^+} - C.$$

$$\text{From the 1st motor eq'n, } 0 = v \Big|_{t=0^+} - Ri \Big|_{t=0^+} - Kw \Big|_{t=0^+}$$

$$v(0^+) = 0V \text{ from problem statement.}$$

$$w(0^+) = 2 \text{ r/s as noted earlier.}$$

$$\therefore i(t=0^+) = \frac{0V - K \cdot 2 \text{ r/s}}{R} = \frac{-4 \text{ Nm/A} \cdot 2 \text{ r/s}}{2 \Omega}$$

$$i(t=0^+) = -4 \text{ A}$$

$$P_J(0^+) = J \cdot w(0^+) \cdot \left. \frac{dw}{dt} \right|_{t=0^+} = \underbrace{(K i(0^+) - C)}_{J \cdot \left. \frac{dw}{dt} \right|_{t=0^+}} w(0^+)$$

$$P_J(0^+) = [4 \text{ Vs} \cdot (-4 \text{ A}) - 8 \text{ Ws}] \cdot 2 \text{ r/s} \Big|_{t=0^+}$$

$$P_J(0^+) = -24 \cdot 2 \text{ W} = -48 \text{ W}$$

Note: the motor acts like a generator producing $i = -4 \text{ A}$ at $t = 0^+$.