

3.3)(a) WITH THE VALUES GIVEN IN THE PROBLEM IT FOLLOWS THAT:

FROM (3.2.5):  $\Gamma_{IN} = 0.671 \angle 160.72^\circ$

FROM (3.2.6):  $\Gamma_{OUT} = 0.615 \angle -82.8^\circ$

FROM (3.2.1):  $G_T = 8.575$  OR  $9.33 \text{ dB}$

FROM (3.2.3):  $G_p = 9.487$  OR  $9.77 \text{ dB}$

FROM (3.2.4):  $G_A = 8.745$  OR  $9.42 \text{ dB}$

(b)  $P_{AVS} = \frac{|E_1|^2}{8 \text{Re}[Z_1]} = \frac{10^2}{8(50)} = 0.25 \text{ W}$ ,  $M_{\lambda} = \frac{G_T}{G_p} = \frac{8.575}{9.487} = 0.904$

$P_{IN} = P_{AVS} M_{\lambda} = 0.25(0.904) = 0.226 \text{ W}$

$P_L = G_p P_{IN} = 9.487(0.226) = 2.144 \text{ W}$

$P_{AVN} = G_A P_{AVS} = 8.745(0.25) = 2.186 \text{ W}$

3.4)  $\Gamma_{\lambda} = 0$  AND  $\Gamma_L = 0.5 \angle 90^\circ$ . HENCE:

$G_T = G_{TU} = 11.294$  OR  $10.53 \text{ dB}$

$G_p = 22.145$  OR  $13.45 \text{ dB}$

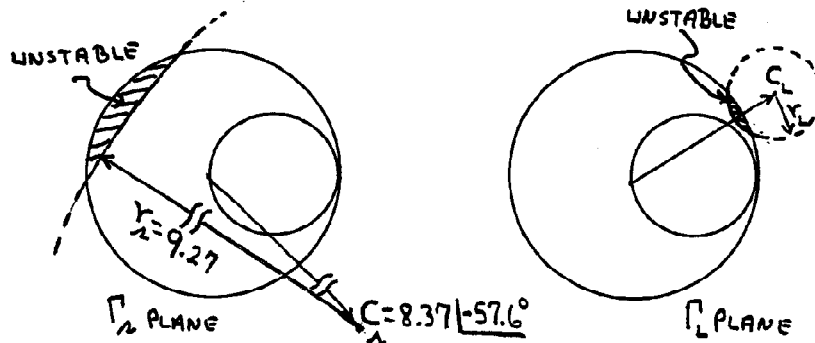
$G_A = 21.33$  OR  $13.29 \text{ dB}$

3.7) (a)  $K = 1.294$ ,  $\Delta = 0.386 \angle 134.2^\circ$   $\therefore$  UNCONDITIONALLY STABLE.

(b)  $K = 0.909$ ,  $\Delta = 0.402 \angle -65.04^\circ$   $\therefore$  POTENTIALLY UNSTABLE.

INPUT STABILITY CIRCLE  $\begin{cases} r_{\lambda} = 9.27 \\ C_{\lambda} = 8.37 \angle -57.6^\circ \end{cases}$

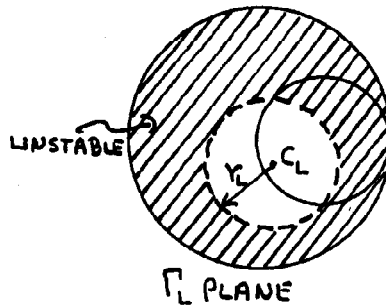
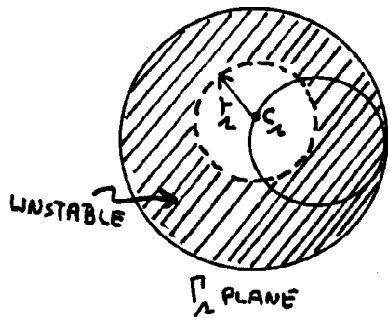
OUTPUT STABILITY CIRCLE  $\begin{cases} r_L = 0.19 \\ C_L = 1.18 \angle 29.8^\circ \end{cases}$



(c)  $K=1.202$ ,  $\Delta=1.76 \angle 18.5^\circ$   $\therefore$  POTENTIALLY UNSTABLE

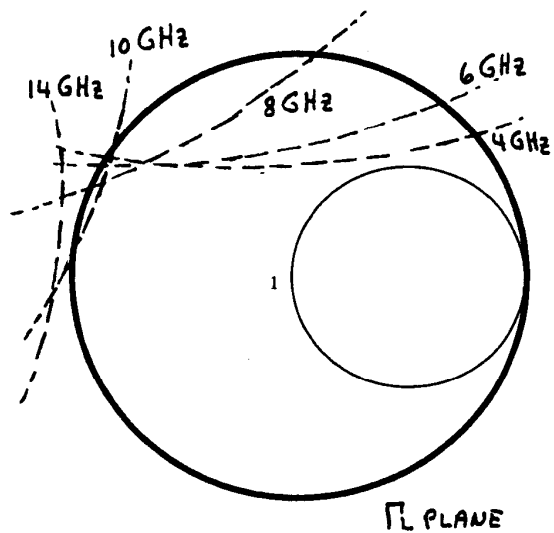
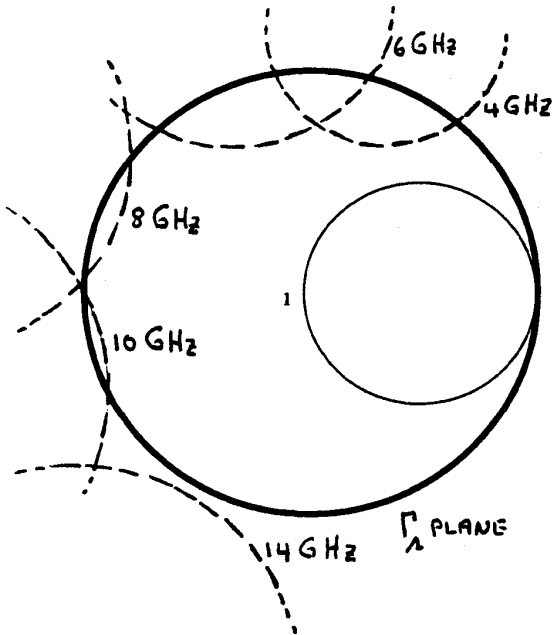
INPUT STABILITY CIRCLE  $\left\{ \begin{array}{l} \gamma_{\lambda} = 0.518 \\ C_{\lambda} = 0.152 \angle 82.1^\circ \end{array} \right.$

OUTPUT STABILITY CIRCLE  $\left\{ \begin{array}{l} \gamma_L = 0.494 \\ C_L = 0.239 \angle -58^\circ \end{array} \right.$



3.8)

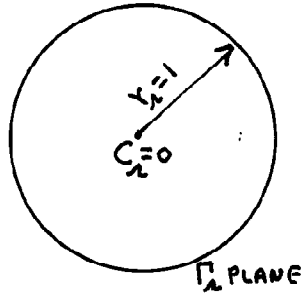
$f$ (GHz)	$K$	$\Delta$	STABILITY CIRCLE	STABILITY CIRCLE
4	0.412	$0.65 \angle -90.3^\circ$	$\gamma_{\lambda} = 0.444, C_{\lambda} = 1.25 \angle 80.9^\circ$	$\gamma_L = 3.79, C_L = 4.3 \angle 91.4^\circ$
6	0.56	$0.57 \angle -131.1^\circ$	$\gamma_{\lambda} = 0.604, C_{\lambda} = 1.43 \angle 111.6^\circ$	$\gamma_L = 6.316, C_L = 6.93 \angle 1107.8^\circ$
8	0.78	$0.43 \angle 174.9^\circ$	$\gamma_{\lambda} = 0.789, C_{\lambda} = 1.69 \angle 152.6^\circ$	$\gamma_L = 7.39, C_L = 8.2 \angle 126.1^\circ$
10	0.89	$0.32 \angle 114^\circ$	$\gamma_{\lambda} = 0.759, C_{\lambda} = 1.72 \angle -171.8^\circ$	$\gamma_L = 3.49, C_L = 4.41 \angle 150.1^\circ$
14	1.33	$0.17 \angle -2.4^\circ$	$\gamma_{\lambda} = 0.513, C_{\lambda} = 1.62 \angle -110.2^\circ$	$\gamma_L = 1.87, C_L = 3.08 \angle -171.7^\circ$



3.9 (a)  $K=1, \Delta=1$

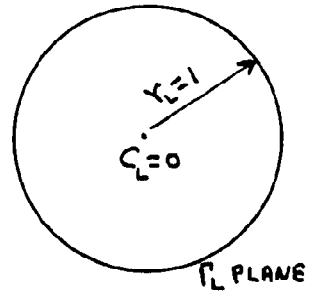
INPUT  
STABILITY  
CIRCLE:

$$\begin{cases} \gamma_{\lambda} = 1 \\ C_{\lambda} = 0 \end{cases}$$



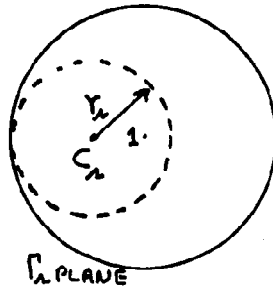
OUTPUT  
STABILITY  
CIRCLE:

$$\begin{cases} \gamma_L = 1 \\ C_L = 0 \end{cases}$$

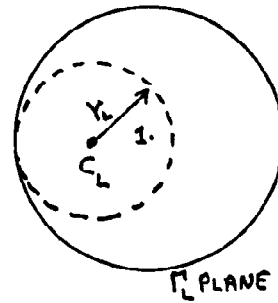


(b)  $K=1, \Delta=-2.414$

$$\begin{cases} \gamma_{\lambda} = 0.55 \\ C_{\lambda} = 0.45 \angle 180^{\circ} \end{cases}$$

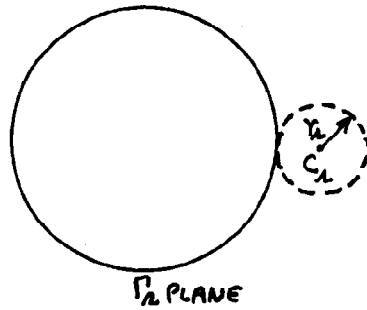


$$\begin{cases} \gamma_L = 0.55 \\ C_L = 0.45 \angle 180^{\circ} \end{cases}$$

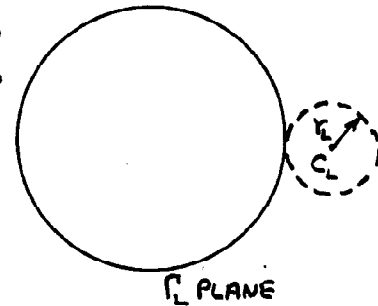


(c)  $K=1, \Delta=0.415$

$$\begin{cases} \gamma_{\lambda} = 0.26 \\ C_{\lambda} = 1.26 \end{cases}$$

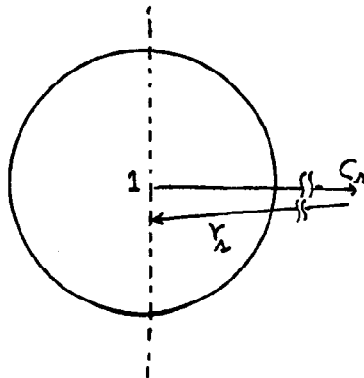


$$\begin{cases} \gamma_L = 0.26 \\ C_L = 1.26 \end{cases}$$

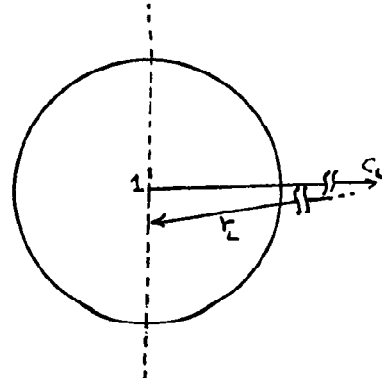


(d)  $K=0, \Delta=-1$

$$\begin{cases} \gamma_{\lambda} = \infty \\ C_{\lambda} = \infty \end{cases}$$



$$\begin{cases} \gamma_L = \infty \\ C_L = \infty \end{cases}$$



3.14) FOR THIS TRANSISTOR:  $K = 0.532$ ,  $\Delta = 0.617 \angle -85.4^\circ$

$$r_L = 1.96$$

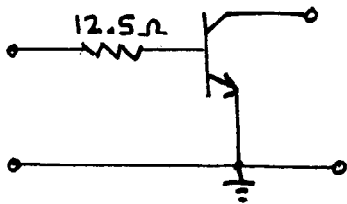
$$C_L = 2.64 \angle 116.7^\circ$$

$$r_L = 0.576$$

$$C_L = 1.4 \angle 41.5^\circ$$

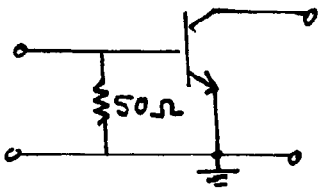
AT POINT A:  $r = 0.25$

$$\therefore R = 0.25(50) = 12.5 \Omega$$



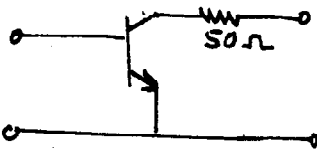
AT POINT B:  $g = 1$

$$\therefore G = \frac{1}{50} = 20 \text{ mS (OR } 50 \Omega)$$



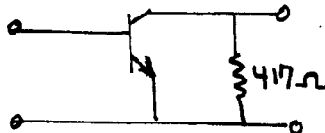
AT POINT C:  $r = 1$

$$\therefore R = 1(50) = 50 \Omega$$



AT POINT D:  $g = 0.12$

$$G = \frac{0.12}{50} = 2.4 \text{ mS (OR } 417 \Omega)$$

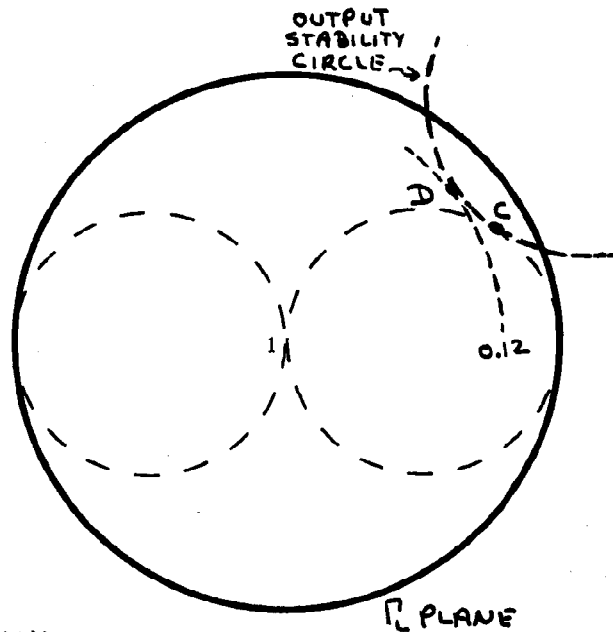
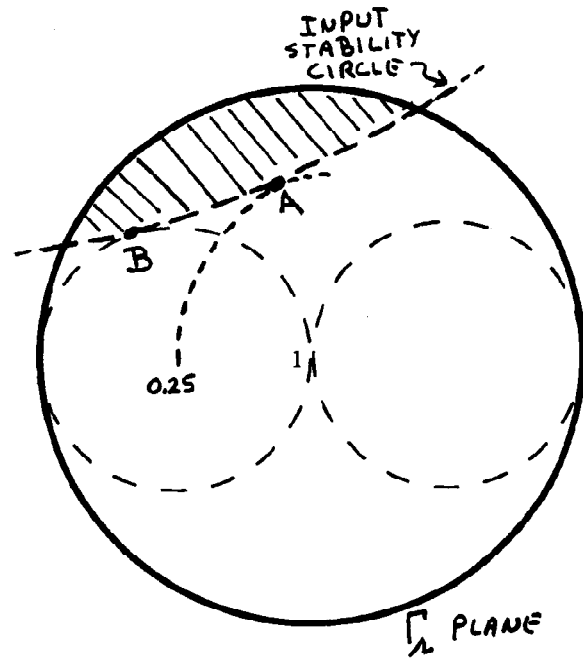


FOR THIS CIRCUIT IT FOLLOWS THAT:  $S_{11} = 0.695 \angle -77.3^\circ$ ,  $S_{12} = 0.03 \angle 42.5^\circ$ ,

$$S_{21} = 5.13 \angle 124.1^\circ, \text{ AND } S_{22} = 0.665 \angle -25.8^\circ.$$

HENCE,  $K = 1.02$  AND  $\Delta = 0.488 \angle -84.7^\circ$

AND THE CIRCUIT IS UNCONDITIONALLY STABLE.



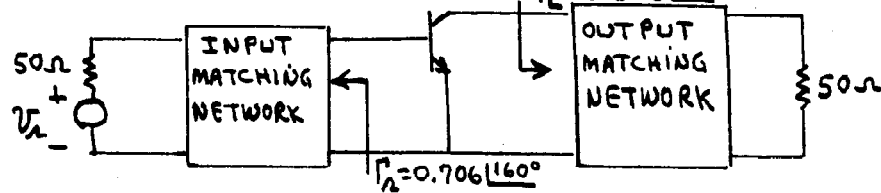
3.16) (a) For  $G_{TU, \max}$ :  $\Gamma_a = S_{11}^* = 0.706 \angle 160^\circ$  AND  
 $\Gamma_L = S_{22}^* = 0.508 \angle 20^\circ$ .

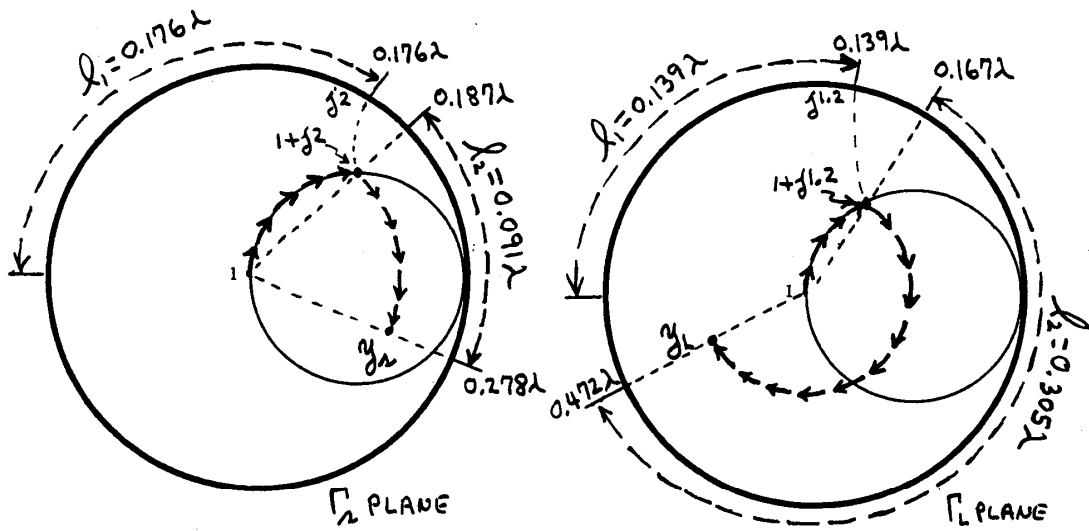
$$G_{a, \max} = \frac{1}{1 - |S_{11}|^2} = \frac{1}{1 - (0.706)^2} = 1.99 \text{ OR } 3 \text{ dB}$$

$$G_o = |S_{21}|^2 = (5.01)^2 = 25.1 \text{ OR } 14 \text{ dB}$$

$$G_{L, \max} = \frac{1}{1 - |S_{22}|^2} = \frac{1}{1 - (0.508)^2} = 1.35 \text{ OR } 1.3 \text{ dB}$$

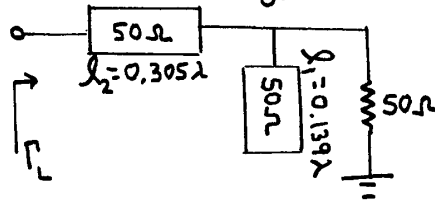
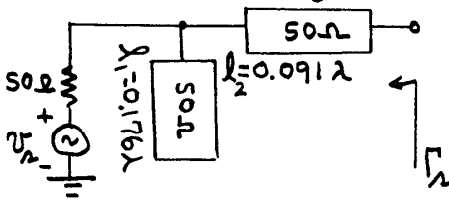
$$G_{TU, \max} = 3 + 14 + 1.3 = 18.3 \text{ dB}$$



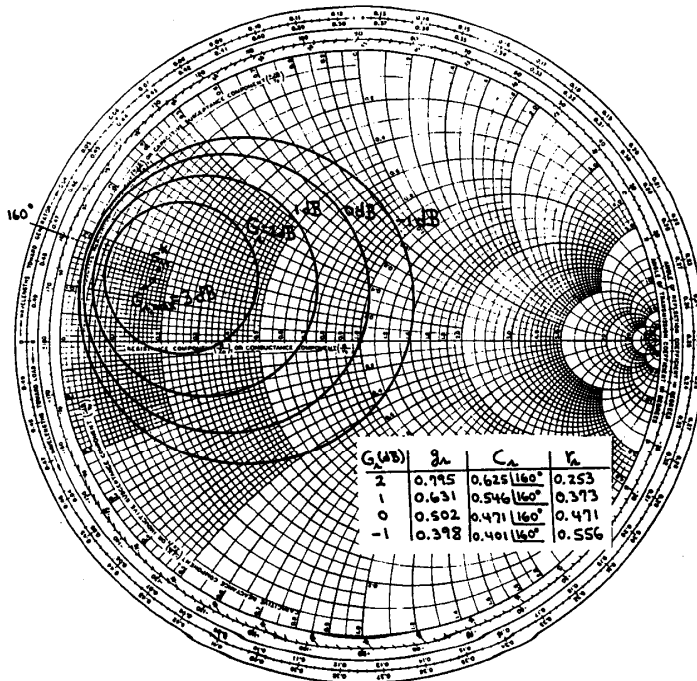


$$\Gamma_2 = 0.706 \angle 160^\circ, \quad Y_2 = \frac{1}{Z_2} = 2.9 - j2.8$$

$$\Gamma_L = 0.508 \angle 20^\circ, \quad Y_L = \frac{1}{Z_L} = 0.335 - j0.157$$



(b)



3.17) (a) THE INPUT RESISTANCE IS CALCULATED AS FOLLOWS :

$$\Gamma_{IN} = S_{11} = 2.3 \angle -135^\circ, \quad Z_{IN} = 50(-0.45 - j0.34) = -22.48 - j17.04 \Omega.$$

$Z_{IN}$  CAN ALSO BE CALCULATED USING THE SMITH CHART.

PLOT  $\frac{1}{S_{11}} = 0.435 \angle -135^\circ$  AND READ  $Z_{IN} = 50(-0.45 - j0.34) = -22.5 - j17 \Omega$

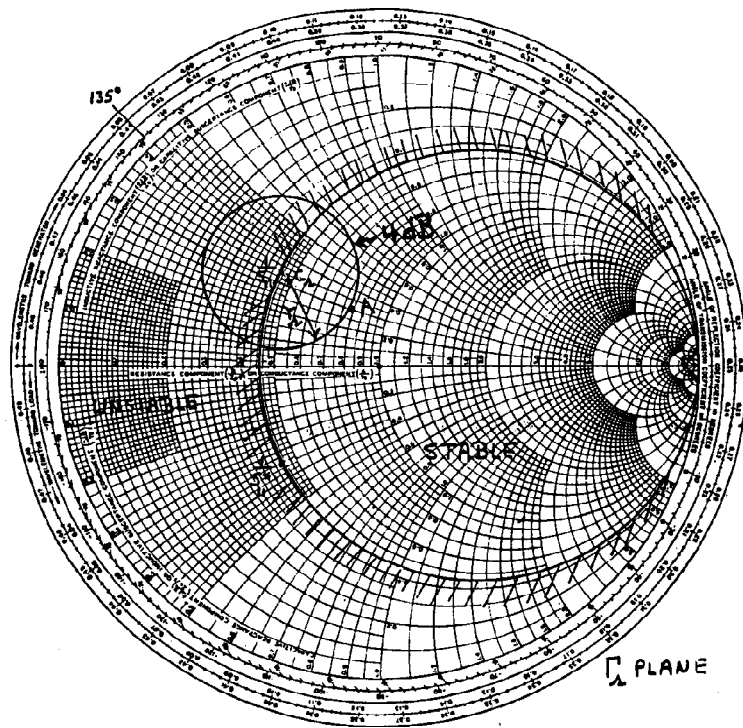
FOR  $G_n = 4 \text{ dB}$ ,  $g_n = 2.512 [1 - (2.3)^2] = -10.78$

FROM (3.4.11) AND (3.4.12):  $C_n = 0.404 \angle 135^\circ$  AND  $r_n = 0.24$

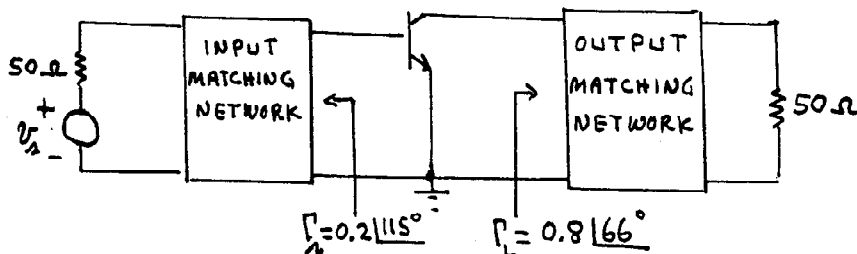
(b) AT POINT A,  $\Gamma_n$  HAS THE LARGEST REAL PART ON THE  $G_n = 4 \text{ dB}$  CIRCLE. THAT IS,

$$\Gamma_n = 0.2 \angle 115^\circ$$

THE INPUT MATCHING CIRCUIT MUST TRANSFORM  $50 \Omega$  TO  $\Gamma_n = 0.2 \angle 115^\circ$ .

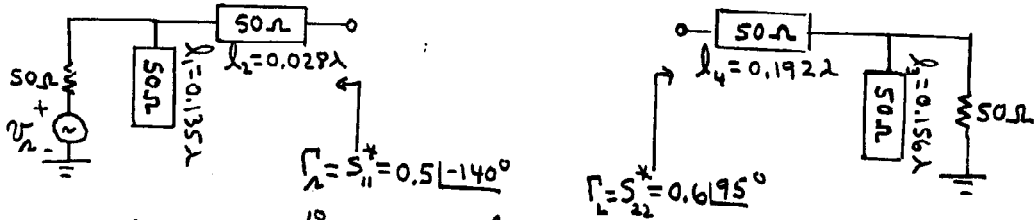


(c) DESIGN FOR  $\Gamma_n = 0.2 \angle 115^\circ$  AND  $\Gamma_L = S_{22}^* = 0.8 \angle 66^\circ$ . THEN,  
 $G_n = 4 \text{ dB}$ ,  $G_o = |S_{21}|^2 = 16$  (OR  $12.04 \text{ dB}$ ),  $G_{L,max} = \frac{1}{1 - (0.8)^2} = 2.78$  (OR  $4.4 \text{ dB}$ )  
 $\therefore G_{TW}(\text{dB}) = G_n + G_o + G_{L,max} = 4 + 12.04 + 4.4 = 20.4 \text{ dB}$



3.18) (a)  $G_{T, \max} = \frac{1}{1-(0.5)^2} = 1.33$  OR 1.25 dB,  $G_{L, \max} = \frac{1}{1-(0.6)^2} = 1.563$  OR 1.94 dB  
 $G_o = |S_{21}|^2 = 25$  OR 13.98 dB,  $\therefore G_{T, \max} = 1.25 + 13.98 + 1.94 = 17.2$  dB

(b) A MATCHING NETWORK DESIGN AT 900 MHz IS:



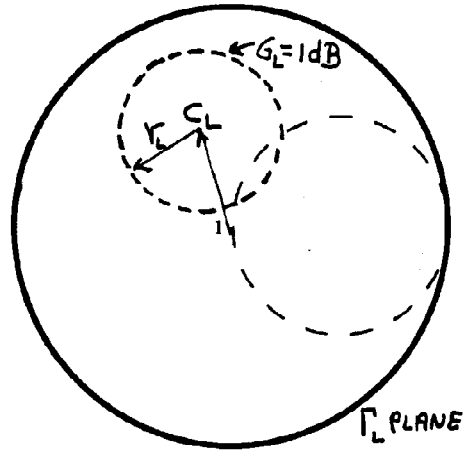
At 900 MHz:  $\lambda = \frac{3 \times 10^{10}}{9 \times 10^8} = 33.3$  cm,  $l_1 = 0.135 \lambda = 4.496$  cm,  
 $l_2 = 0.028 \lambda = 0.932$  cm,  $l_3 = 0.156 \lambda = 5.195$  cm,  $l_4 = 0.192 \lambda = 6.394$  cm

(c)  $g_L = \frac{G_L}{G_{L, \max}} = \frac{1.259}{1.563} = 0.805$

From (3.4.11) AND (3.4.12):

$C_L = 0.519 \angle 95^\circ$

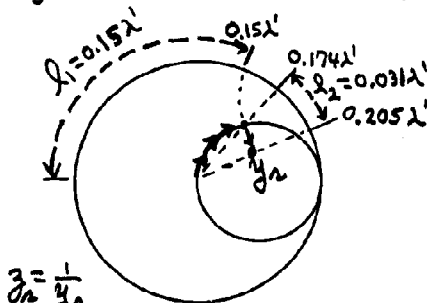
$\Gamma_L = 0.304$



(d) LET  $\lambda' = \frac{c}{f'}$  WHERE  $f' = 1$  GHz,  
 AND  $\lambda = \frac{c}{f}$  WHERE  $f = 900$  MHz.

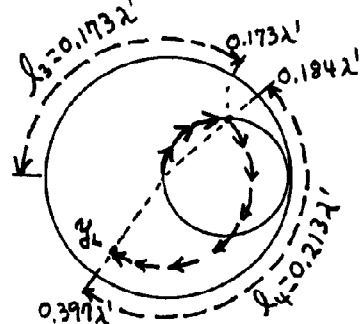
$\therefore \frac{\lambda}{\lambda'} = \frac{f'}{f}$  OR  $\lambda = \frac{f'}{f} \lambda' = \frac{10^9}{9 \times 10^8} \lambda' = 1.11 \lambda'$

$l_1 = 0.135 \lambda = 0.135 (1.11 \lambda') = 0.15 \lambda'$ ,  $l_2 = 0.028 (1.11 \lambda') = 0.031 \lambda'$ ,  
 $l_3 = 0.156 (1.11 \lambda') = 0.173 \lambda'$ ,  $l_4 = 0.192 (1.11 \lambda') = 0.213 \lambda'$



$z_L = \frac{1}{y_L}$   
 $y_L = 1.79 + j1.58$ ,  $\Gamma_L = 0.55 \angle -146^\circ$

$\therefore G_{TU} = \frac{1 - (0.55)^2}{|1 - 0.48 \angle 137^\circ (0.55 \angle -146^\circ)|^2} (4.6)^2$



$z_L = \frac{1}{y_L}$   
 $y_L = 0.28 - j0.72$ ,  $\Gamma_L = 0.693 \angle 74.4^\circ$

$\frac{1 - (0.693)^2}{|1 - 0.57 \angle -99^\circ (0.693 \angle 74.4^\circ)|^2} = 31.97$  OR 15.05 dB



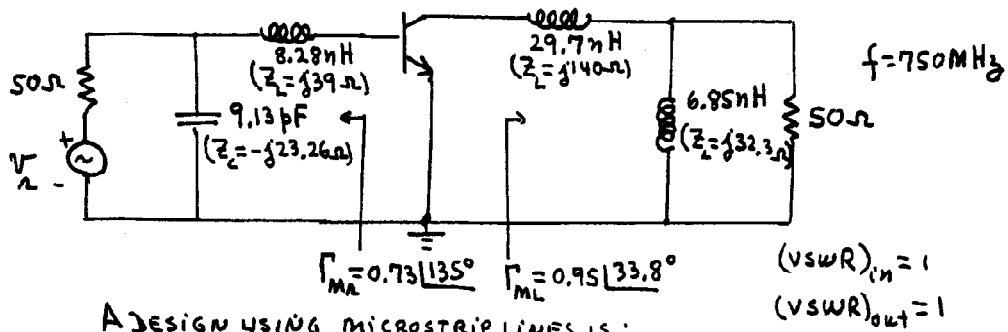
3.21)  $K = 1.03$  AND  $\Delta = 0.324 \angle -64.8^\circ$   $\therefore$  UNCONDITIONALLY STABLE

FROM (3.6.5) :  $\Gamma_{MA} = 0.73 \angle 135^\circ$

FROM (3.6.6) :  $\Gamma_{ML} = 0.95 \angle 33.8^\circ$

FROM (3.6.10) :  $G_{T, \max} = 19.08$  OR  $12.8$  dB

A DESIGN USING LUMPED ELEMENTS IS :



A DESIGN USING MICROSTRIP LINES IS :

