

Question: When is ϵ more than just w ?

True signal model of the form ~~$a + bn + cn^2$~~ $a + bn + cn^2$
but we are fitting only $\hat{a} + \hat{b}n$.

In a given class of models, we can plot the error $J(\hat{\theta})$ vs the number of parameters in the model to get an idea of the appropriate number of parameters.

Note 1: LS error will always decrease with noisy data even if we increase the # of parameters beyond the appropriate #.

Think of the geometric interpretation of LS. By adding a new column to H (basis vector) the signal of model can always get closer to x . In effect, what is happening is the model is starting to capture some of the noise. This is known as overfitting.

Note 2: Order-recursive LS is a method for incrementally updating $\hat{\theta}$ without having to perform $\hat{\theta}_p = (H_p^T H_p)^{-1} H_p^T x$ every time we add a column to H .

In fact, if H forms an orthonormal basis (as in Fourier analysis) $\hat{\theta}_p = H^T x = \begin{bmatrix} h_1^T \\ h_2^T \\ \vdots \\ h_p^T \end{bmatrix} \begin{bmatrix} x[0] \\ \vdots \\ x[p] \end{bmatrix}$

So when we add h_{p+1} to H all we need to do is

$\hat{\theta}_{p+1} = \begin{bmatrix} \hat{\theta}_p \\ h_{p+1}^T x \end{bmatrix}$ → This part doesn't change due to orthonormality of H .

SEQUENTIAL L.S.

Data set increasing with time. For $x[0], \dots, x[N-1]$ we have $\hat{\theta}$, now we get $x[N]$. How does $\hat{\theta}$ change? Do we have to compute it from scratch?

Example: $x[n] = A + w[n]$ D.C. level

Define $\hat{A}[N]$ to be the L.S. estimator for A from the dataset $x[0], \dots, x[N]$

We know that:

$$\hat{A}[N-1] = \frac{1}{N} \sum_{n=0}^{N-1} x[n] \quad ; \text{ and}$$

$$\hat{A}[N] = \frac{1}{N+1} \sum_{n=0}^N x[n]$$

We can rewrite $\hat{A}[N]$ as

$$\hat{A}[N] = \frac{1}{N+1} \left[\underbrace{\left(\sum_{n=0}^{N-1} x[n] \right)}_{N \hat{A}[N-1]} + x[N] \right]$$

$$\textcircled{**} = \frac{N}{N+1} \hat{A}[N-1] + \frac{1}{N+1} x[N]$$

This is a weighted average. The weight for $x[N]$ goes to 0 as N becomes large, whereas the weight for $\hat{A}[N-1]$ goes to 1. Why?

Again rearranging the terms

$$\textcircled{*} \hat{A}[N] = \hat{A}[N-1] + \underbrace{\frac{1}{N+1}}_{\text{correction weight}} \underbrace{(x[N] - \hat{A}[N-1])}_{\text{correction to estimate}}$$

How about $\underbrace{J_{\min}}_{J(\hat{\theta})}$ as a function of N ?

$$J_{\min}[N] = \sum_{n=0}^N (x[n] - \hat{A}[N])^2$$

$$= \left(\sum_{n=0}^{N-1} (x[n] - \hat{A}[N])^2 \right) + (x[N] - \hat{A}[N])^2$$

$$= \sum_{n=0}^{N-1} \left(x[n] - \hat{A}[N-1] - \frac{1}{N+1} (x[N] - \hat{A}[N-1]) \right)^2$$

from (*)

$$+ (x[N] - \hat{A}[N])^2$$

$$= \sum_{n=0}^{N-1} (x[n] - \hat{A}[N-1])^2 \rightarrow J_{\min}[N-1]$$

$$- \frac{2}{N+1} \left[\sum_{n=0}^{N-1} (x[n] - \hat{A}[N-1]) \right] (x[N] - \hat{A}[N-1])$$

$$+ \frac{N}{(N+1)^2} (x[N] - \hat{A}[N-1])^2$$

$$+ (x[N] - \hat{A}[N])^2 \rightarrow \left(x[N] - \frac{N}{N+1} \hat{A}[N-1] - \frac{1}{N+1} x[N] \right)^2$$

$$= J_{\min}[N-1]$$

$$+ \frac{N}{(N+1)^2} (1+N) (x[N] - \hat{A}[N-1])^2$$

$$= \left(\frac{N}{N+1} x[N] - \frac{N}{N+1} \hat{A}[N-1] \right)^2$$

$$= J_{\min}[N-1]$$

$$= \frac{N^2}{(N+1)^2} (x[N] - \hat{A}[N-1])^2$$

$$+ \frac{N}{N+1} (x[N] - \hat{A}[N-1])^2$$

error can not decrease with increasing N . Why not?

A generalization of the previous result:

Let data point n have variance σ_n^2 , then a weighted least squares estimator is

$$\hat{A}[N-1] = \frac{\sum_{n=0}^{N-1} \frac{1}{\sigma_n^2} x[n]}{\sum_{n=0}^{N-1} 1/\sigma_n^2}$$

$$\textcircled{1} \hat{A}[N] = \hat{A}[N-1] + \underbrace{\frac{1/\sigma_N^2}{\sum_{n=0}^N 1/\sigma_n^2}}_{K[N]} (x[N] - \hat{A}[N-1])$$

$K[N]$ = gain factor for N 'th correction

$$0 \leq K[N] \leq 1$$

$$\hookrightarrow \sigma_N^2 \rightarrow 0$$

if all $\sigma_n^2 = \sigma^2$ then $K[N] = 1/(N+1)$ as before

* $K[N]$ can be rewritten as

$$\textcircled{2} K[N] = \frac{1/\sigma_N^2}{1/\sigma_N^2 + 1/\text{var}(\hat{A}[N-1])}$$

$$= \frac{\text{var}(\hat{A}[N-1])}{\text{var}(\hat{A}[N-1]) + \sigma_N^2}$$

from variance of sum of random vars.

Equations $\textcircled{2}$ & $\textcircled{1}$ define a recursion. Start with

$$\hat{A}[0] = x[0] \text{ and } \text{var}(\hat{A}[0]) = \sigma_0^2$$

Vector case

C : data covariance. Diagonal with $\sigma_0^2, \sigma_1^2, \dots, \sigma_n^2$

Let $H[n] = \begin{bmatrix} H[n-1] \\ h^T[n] \end{bmatrix}$ Adding a row for data point n .

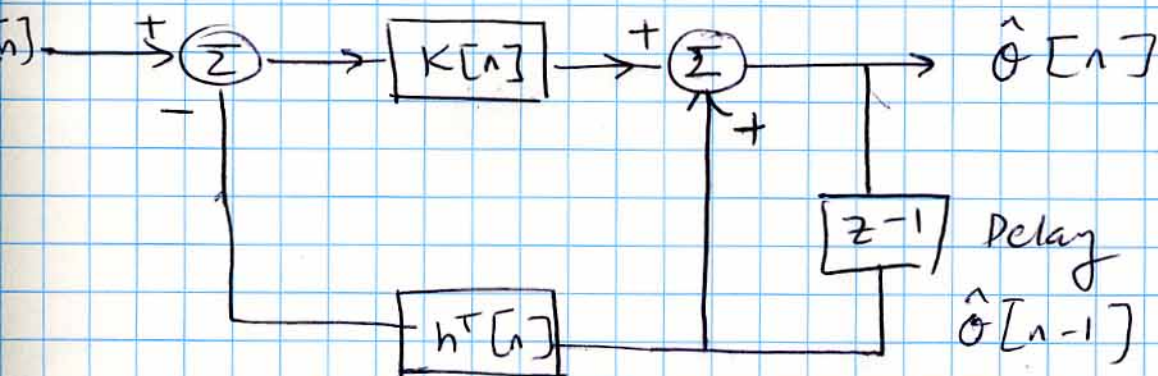
* $\hat{\theta}[n] = \left(H^T[n] C^{-1}[n] H[n] \right)^{-1} H^T[n] C^{-1}[n] \underline{x}[n]$
 where $\underline{x}[n] = \begin{bmatrix} x[0] \\ \vdots \\ x[n] \end{bmatrix}$

This can be written in recursive way as well

① $\hat{\theta}[n] = \hat{\theta}[n-1] + K[n] \left(x[n] - h^T[n] \hat{\theta}[n-1] \right)$
 ↳ The data point $x[n]$. Not $\underline{x}[n]$

where $K[n] = \frac{\Sigma[n-1] h[n]}{\sigma_n^2 + h^T[n] \underbrace{\Sigma[n-1]}_{\text{covariance matrix for } \hat{\theta}[n-1]} h[n]}$

② $\Sigma[n] = (I - K[n] h^T[n]) \Sigma[n-1]$



2 possible initializations

- Use * to get $\hat{\theta}[p-1]$ Since we need $n \geq p$ for inversion
- Initialize $\hat{\theta}[-1]$ to arbitrary value (0)
 $\Sigma[-1] = \alpha I$ where α is large (low confidence)