

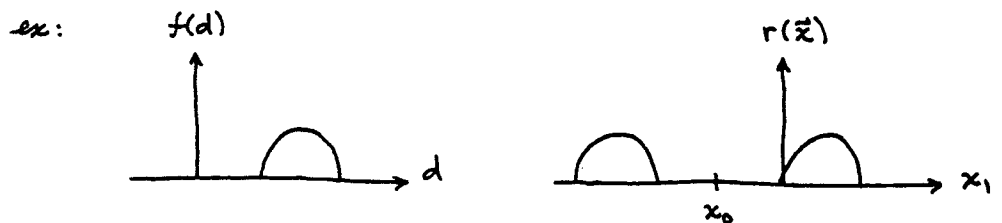
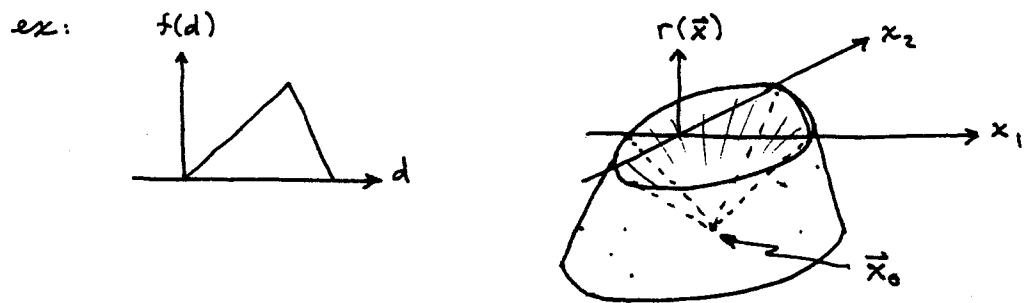
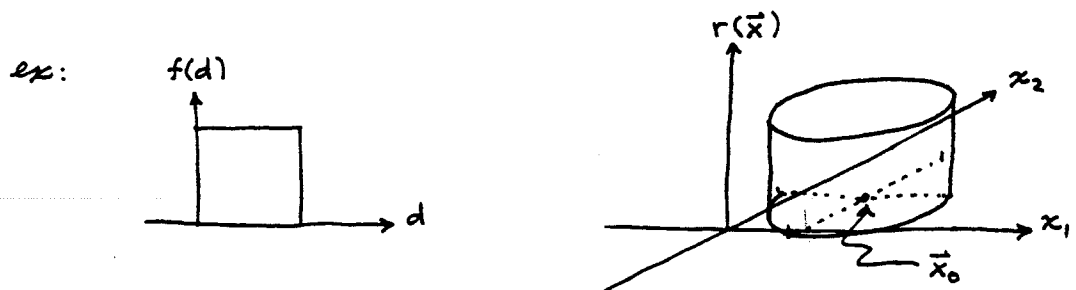
M. E. Cottar
10 Apr 1994

def: $r(\vec{x})$ is a radial basis function \equiv the value of $r(\vec{x})$ depends only on the distance, d , of \vec{x} from a center point \vec{x}_0 . In other words, $r(\vec{x})$ has the following form:

$$r(\vec{x}) = f(d) \text{ and } r(\vec{x})=1 \text{ when } d=0$$

where $d = \sqrt{|\vec{x} - \vec{x}_0|^2}$ is the Euclidean distance from \vec{x} to \vec{x}_0 , ($d \geq 0$ always).

tool: We create radial basis functions by defining $f(d)$ and rotating it about a vertical axis at \vec{x}_0 .



note: $\vec{x} = x_1$ (only one input variable)

note: $\vec{x} = (x_1, \dots, x_N)$ can have more than two dimensions. We just have no way of drawing radial basis functions for $N > 2$.

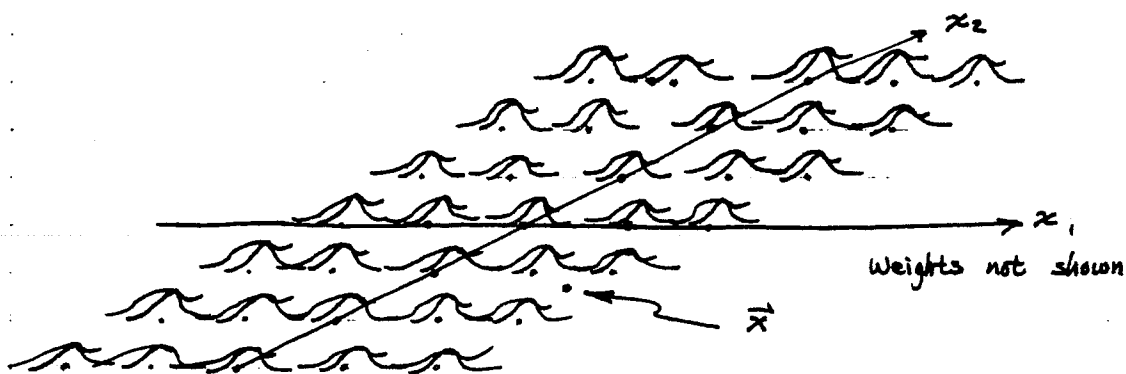
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tool: We create a radial basis function network by taking a weighted sum of radial basis functions whose center points may be placed wherever we wish but are usually placed on a regular grid.

$$f(\vec{x}) = \sum_{j=1}^M w_j r_j(\vec{x})$$

where $r_j(\vec{x})$ is centered at \vec{x}_{0j}

ex: gaussian radial basis functions on regular grid



Each bump (basis function) has an associated weight that may be thought of as changing the height of the bump.

To evaluate $f(\vec{x})$ we determine how far \vec{x} is from the center of every radial basis function. Having found this distance, we can determine the value of $r_j(\vec{x})$. In the picture, $r_j(\vec{x})$ is just the height of the bump $r_j(\vec{x})$ at \vec{x} . We note that \vec{x} is quite far out on the tails of most of the gaussians. Hence, $r_j(\vec{x})$ is small for most of the r_j 's.

Given the $r_j(x)$ values, multiply by weights w_j and sum to get the network output.

Neil Cotton

10 Apr 1994

ex: Network with four gaussian radial basis functions, weights indicated by heights.

$$r_1(\vec{x}) = e^{-(x_1^2 + x_2^2)}$$

$$r_2(\vec{x}) = e^{-[(1-x_1)^2 + x_2^2]}$$

$$r_3(\vec{x}) = e^{-[x_1^2 + (1-x_2)^2]}$$

$$r_4(\vec{x}) = e^{-[(1-x_1)^2 + (1-x_2)^2]}$$

$$w_1 = -\frac{1}{2}$$

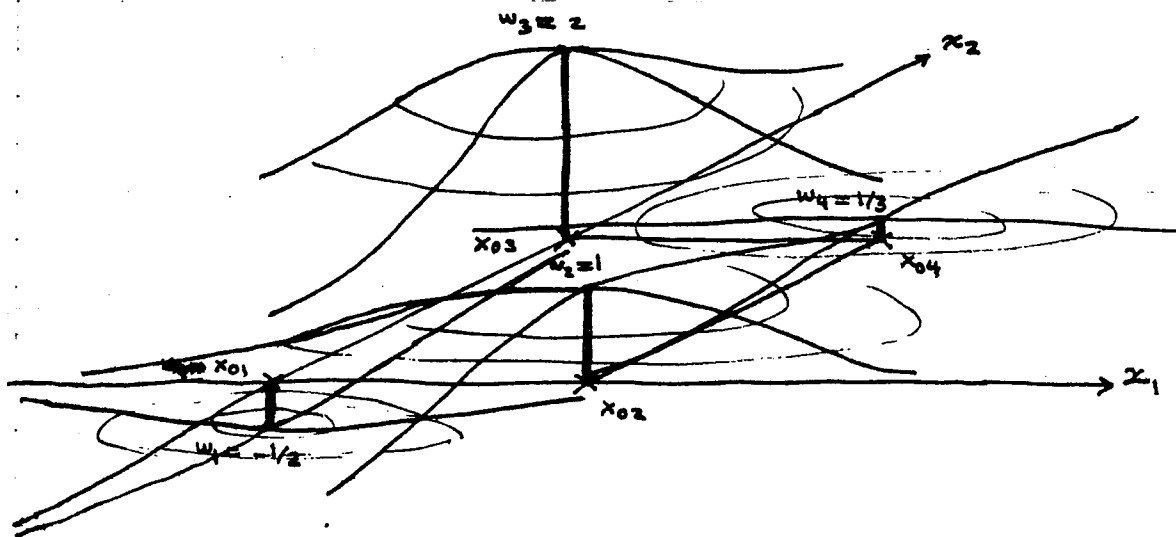
$$w_2 = 1$$

$$x_{01} = (0,0) \quad x_{02} = (1,0)$$

$$w_3 = 2$$

$$w_4 = \frac{1}{3}$$

$$x_{03} = (0,1) \quad x_{04} = (1,1)$$



ex: Evaluate $f(\vec{x})$ for above example with $\vec{x} = (\frac{1}{2}, \frac{1}{2})$

$$r_1(\vec{x}) = e^{-[(\frac{1}{2})^2 + (\frac{1}{2})^2]} = e^{-\frac{1}{2}} = 0.606$$

$$r_2(\vec{x}) = e^{-[(1-\frac{1}{2})^2 + (\frac{1}{2})^2]} = e^{-\frac{1}{2}} = 0.606$$

$$r_3(\vec{x}) = e^{-[(\frac{1}{2})^2 + (1-\frac{1}{2})^2]} = e^{-\frac{1}{2}} = 0.606$$

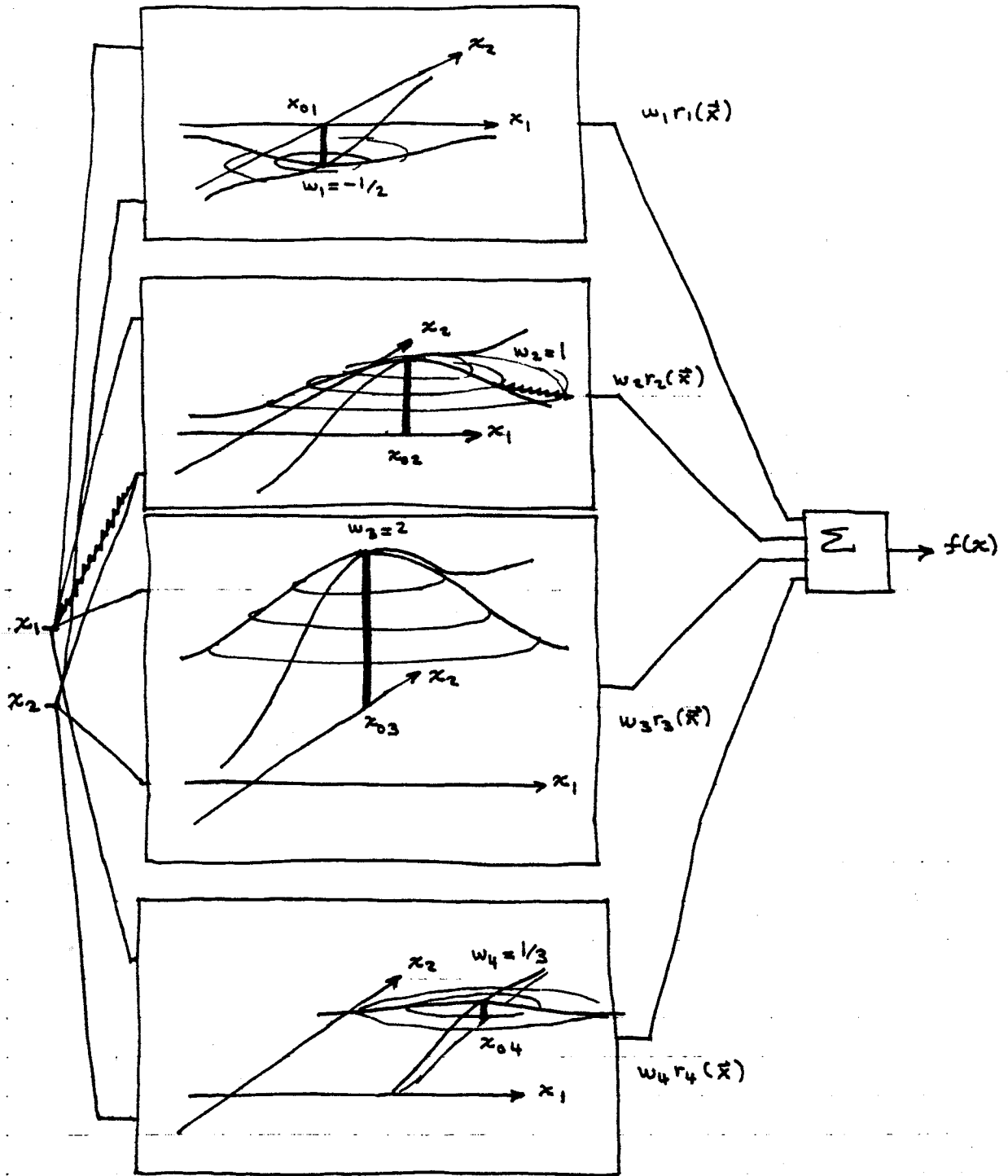
$$r_4(\vec{x}) = e^{-[(1-\frac{1}{2})^2 + (1-\frac{1}{2})^2]} = e^{-\frac{1}{2}} = 0.606$$

$$f(\vec{x}) = \sum_{j=1}^4 w_j r_j(\vec{x}) = -\frac{1}{2} \cdot 0.606 + 1 \cdot 0.606 + 2 \cdot 0.606 + \frac{1}{3} \cdot 0.606 = 1.7$$

Radial Basis Function Networks - Definition

E. Cottler

10 Apr 1994. ex: We can draw the previous example network as follows.



Radial Basis Function Networks - Definition

M. E. Cotton

10 Apr 1994 ex: We can also draw the previous network example as follows.

