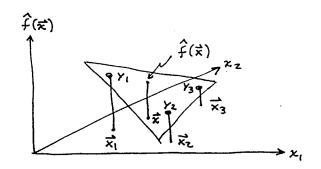
Triangulation - Hyperplane Interpolation

Neil E Cotter 1994

tool: Having found the vertices of the triangle containing \vec{x} , we find the plane passing through the y values for those vertices by solving a matrix equation.



The equation for the plane has the form $y = a_0 \cdot 1 + a_1 \times 1 + a_2 \times 2$, or $\vec{a} \cdot \vec{x}_+ = y$

where $\vec{x}_{+} = (1, x_{1}, x_{2})$ and $\vec{q} = (a_{0}, a_{1}, q_{2})$.

Since the plane passes through the data points we have

$$\vec{a} \cdot \vec{x}_{1+} = y_1$$

$$\vec{a} \cdot \vec{x}_{2+} = y_2$$

$$\vec{a} \cdot \vec{x}_{3+} = y_3$$

$$\begin{array}{ccc}
\sigma_{r} & \begin{bmatrix} -\vec{x}_{1+} & - \\ -\vec{x}_{2+} & - \end{bmatrix} \begin{bmatrix} 1 \\ \vec{q} \end{bmatrix} = \begin{bmatrix} 1 \\ \vec{y} \end{bmatrix}
\end{array}$$

or
$$X = \vec{q} = \vec{y}$$

Thus, $\vec{q} = X^{-1} \vec{y}$.

Having found \vec{a} , we have $\hat{f}(\vec{x}) = \vec{a} \cdot \vec{x}_{+}$.

note: We can compute a ahead of time and store them.