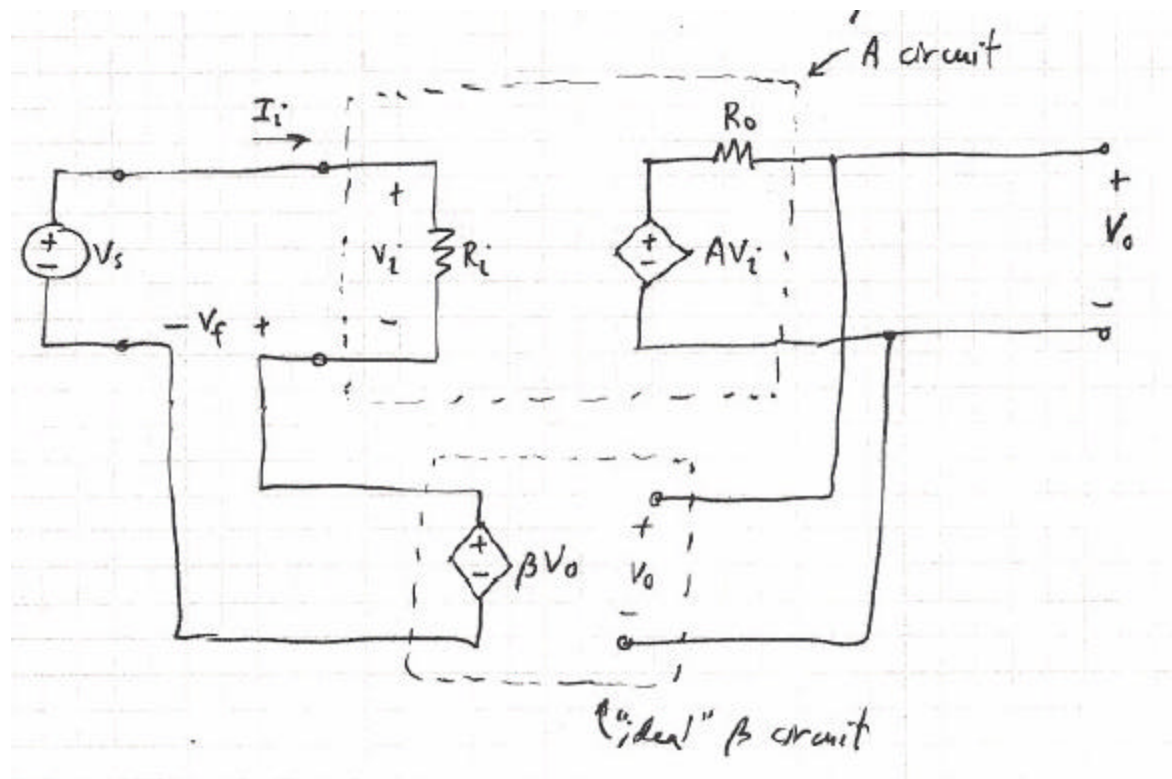
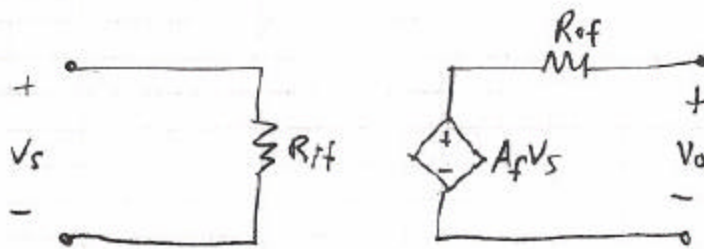


# FEEDBACK/STABILITY

Detailed look at series-shunt feedback:



Equivalent circuit:



$$A_f = 1/(1 + A\beta)$$

$R_{if}$ :

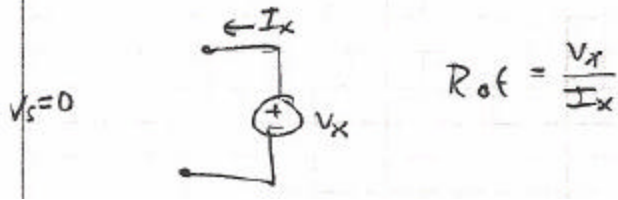
$$R_{if} \equiv \frac{V_s}{I_i} = \frac{V_s}{V_i/R_i} = R_i \frac{V_s}{V_i} = R_i \frac{V_i + V_f}{V_i} = R_i \frac{V_i + \beta A V_i}{V_i}$$

$$V_f = \beta V_o = \beta A V_i$$

$$\Rightarrow R_{if} = R_i(1 + A\beta) \quad \text{*This increase in input resistance is desirable}$$

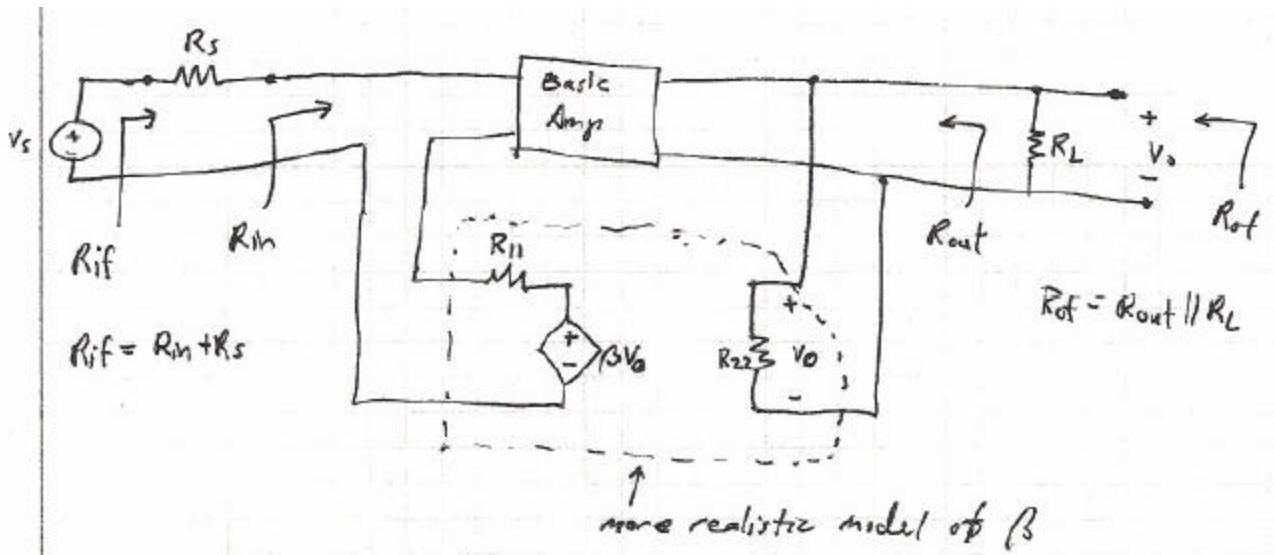
# FEEDBACK/STABILITY

$R_{of}$ :

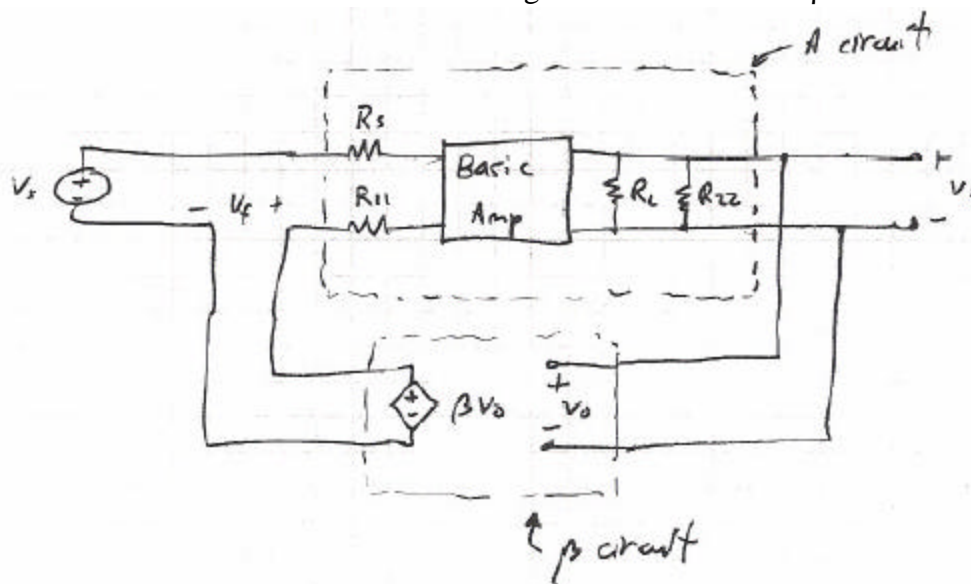


## Series-shunt feedback:

- Nonideal situation for feedback:



- This circuit can be “modified” to get the ideal model of  $\beta$ :



- Need to find  $R_{11}$ ,  $R_{22}$ , and  $\beta$  for different topologies
  - Series-shunt feedback:

# FEEDBACK/STABILITY

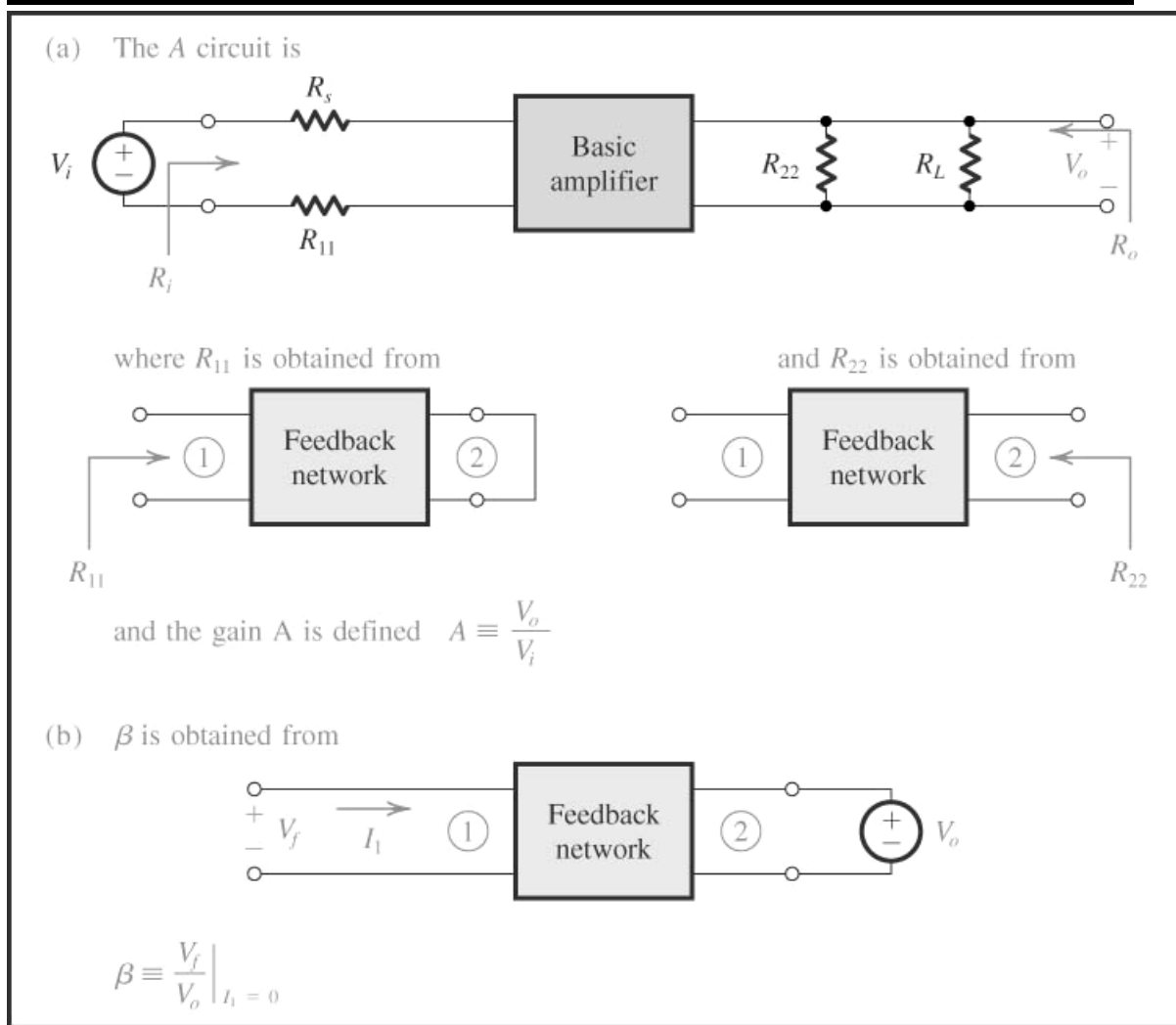


Fig. 8.11 (book)

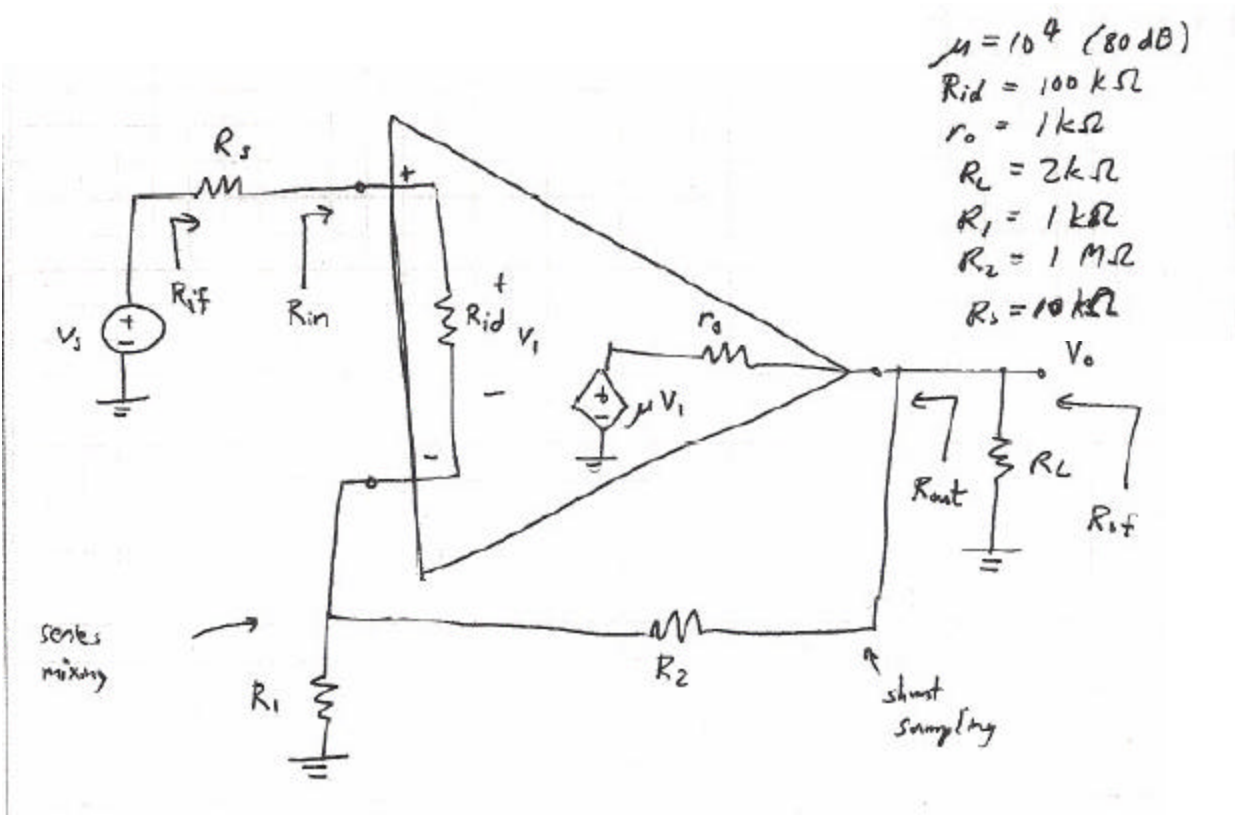
**NOTE: The modified circuit will be different for each feedback topology:**

See Figs. 8.15, 8.16, 8.18, 8.20, 8.22, 8.24

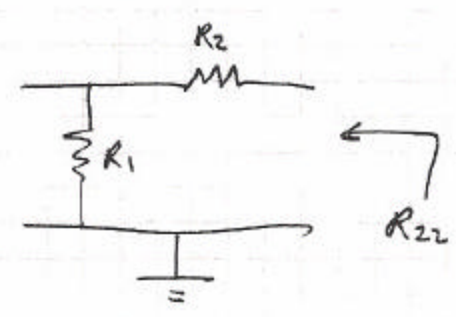
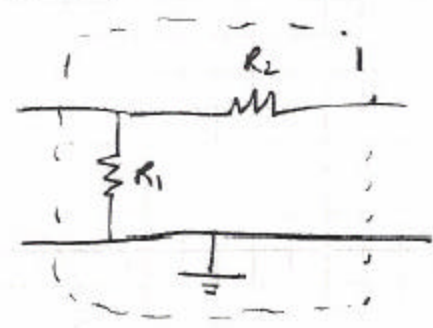
See Table 8.1 for a summary

# FEEDBACK/STABILITY

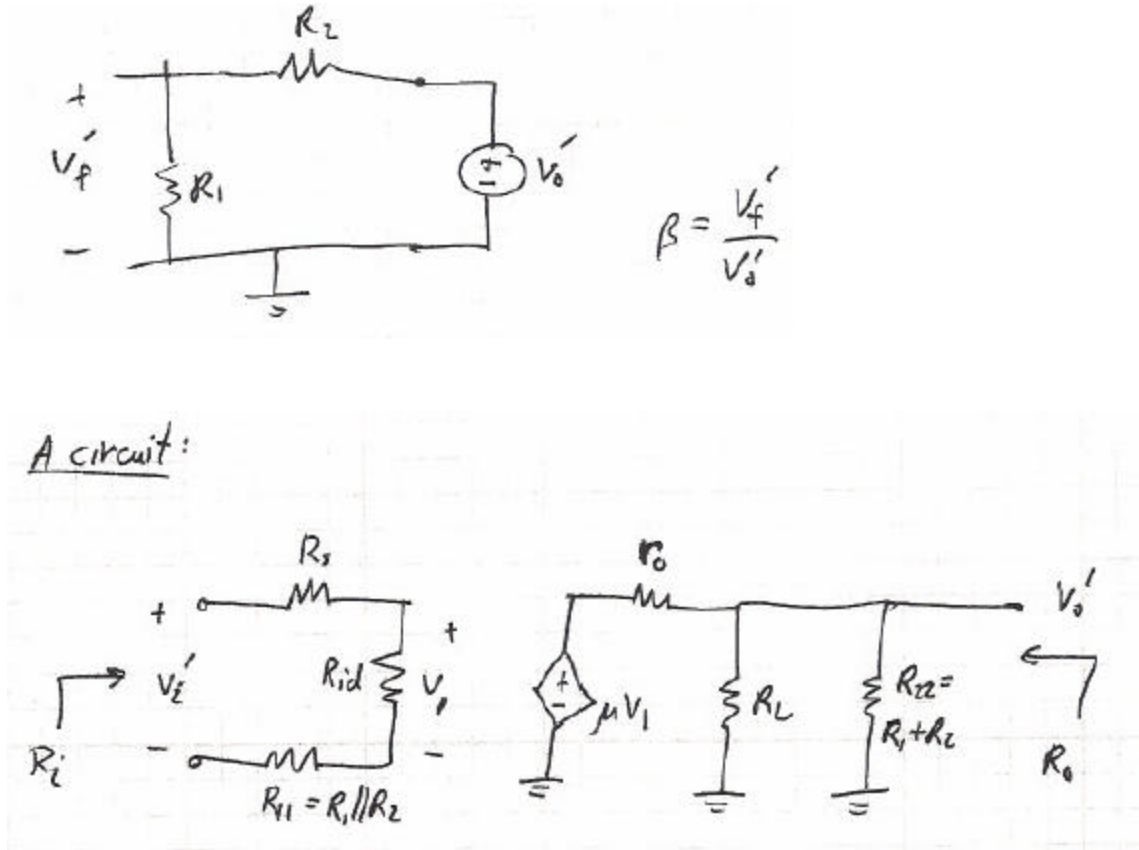
Example 8.1:



Feedback network:



# FEEDBACK/STABILITY



## Stability:

- Negative feedback is stable, why?
- All positive feedback is unstable – leads to oscillations

$$A_f(j\omega) = \frac{A(j\omega)}{1 + A(j\omega)b(j\omega)}$$

Case 1:  $|A(j\omega)b(j\omega)| < 1$

Case 2:  $|A(j\omega)b(j\omega)| = 1$

Case 3:  $|A(j\omega)b(j\omega)| > 1$

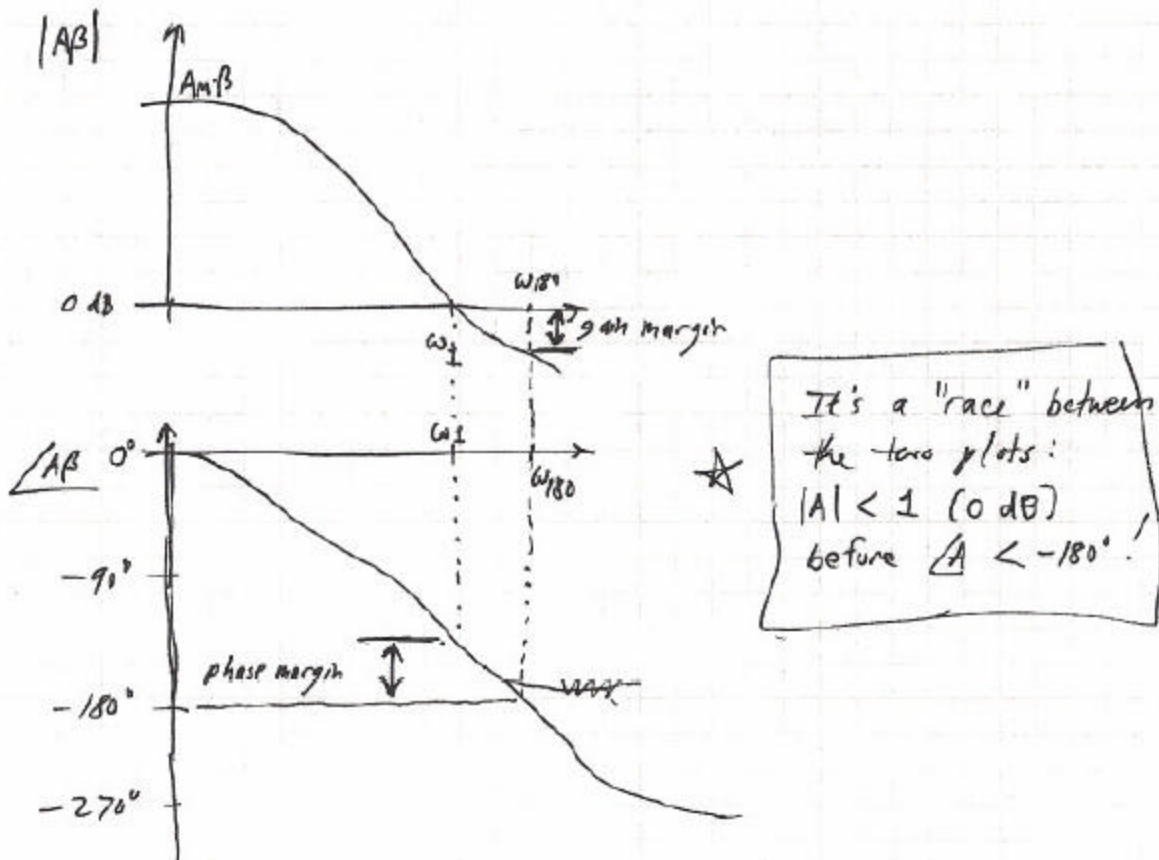
# FEEDBACK/STABILITY

Definitions:

Oscillator=>

Gain margin=>

Phase margin=>



Rule of thumb: Phase margin should be at least  $45^\circ$   
... at least  $60^\circ$  to be safe.

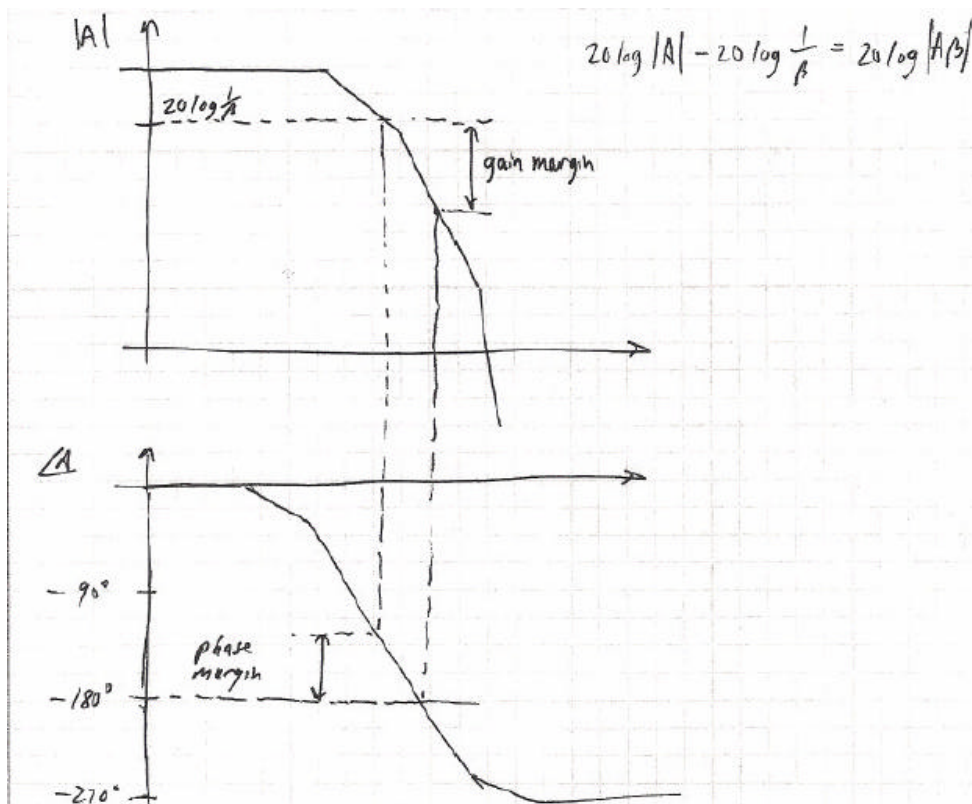
# FEEDBACK/STABILITY

Instead of making Bode plot for loop gain, we can use the Bode plot of just A:

Step 1. Draw magnitude plot for A

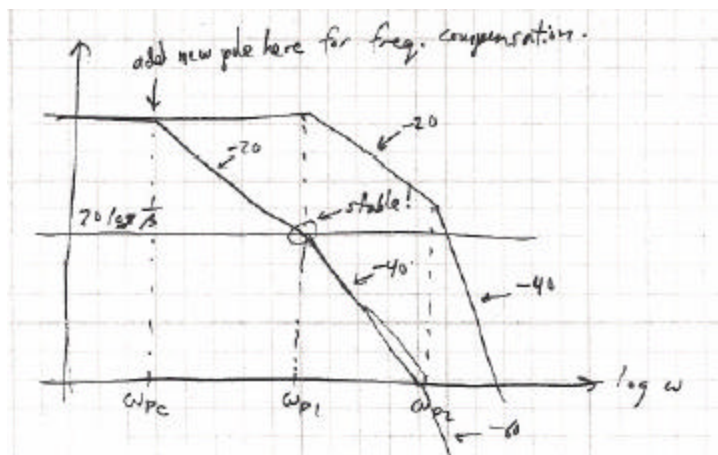
Step 2. Draw a line for  $20 \log(1/\beta)$

Step 3. Can measure gain margin and phase margin from this plot:



## Frequency Compensation:

- Add a pole so that  $20 \log(1/\beta)$  intersects  $|A|$  line at  $-20\text{dB/dec}$ . What is phase after 1<sup>st</sup> pole?
- Add pole  $p_c < p_1, p_2, \dots$  so  $p_1$  becomes 2<sup>nd</sup> pole.



Tradeoff?

# FEEDBACK/STABILITY

Method:

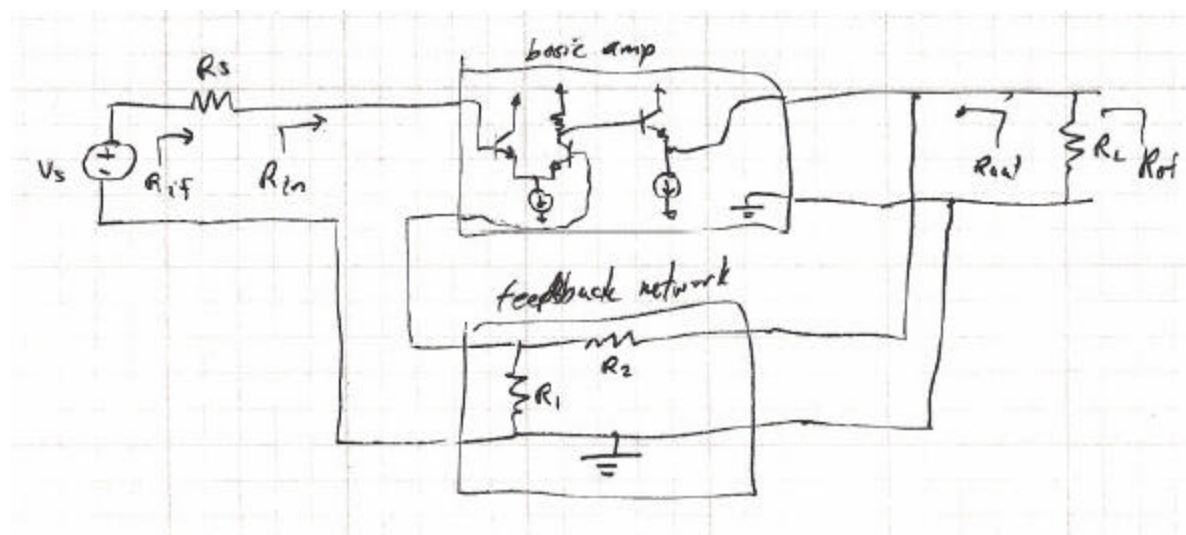
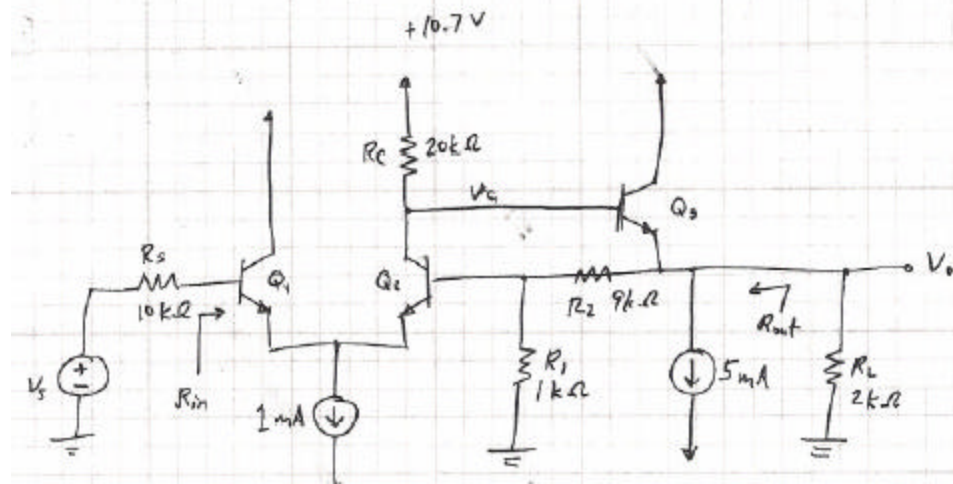
Step 1. Draw magnitude Bode plot of  $|A|$  and straight line at  $20 \log (1/\beta)$

Step 2. Mark point at first pole freq. on  $20 \log (1/\beta)$  line

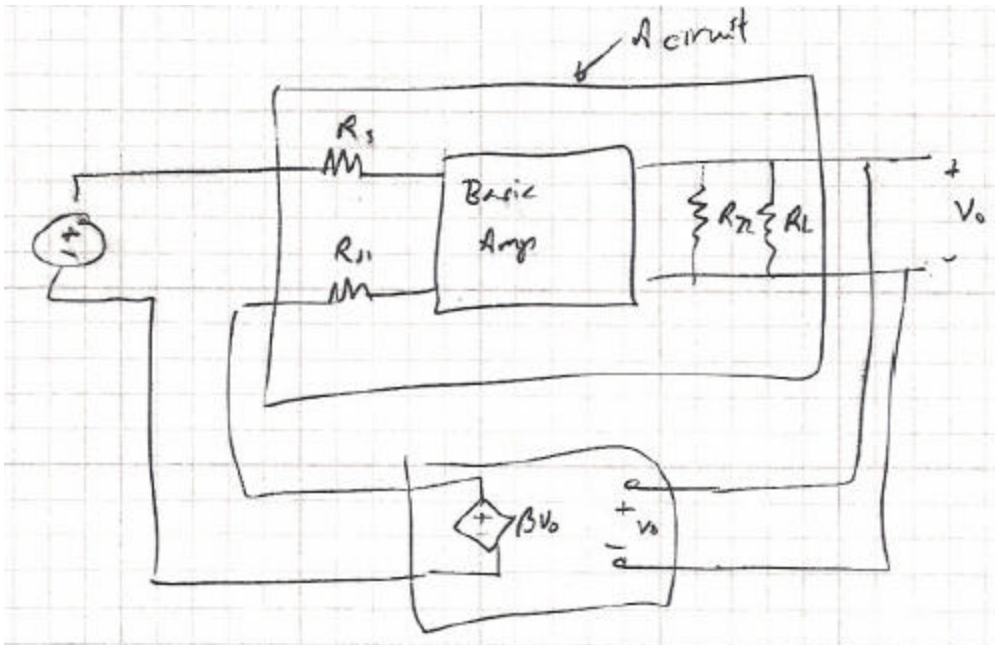
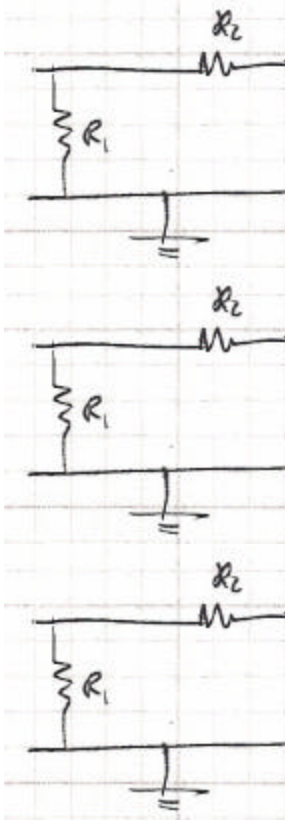
Step 3. Trace a line from the point in Step 2 backwards at a slope of  $-20\text{dB/dec}$ .

Step 4. Note where this line intersects  $|A|$  curve and determine this frequency as the new pole.

Example: Exercise 8.5  $\beta=100$ , series-shunt feedback,  $A$ ,  $\beta$ ,  $A_f$ ,  $R_{in}$ , and  $R_{out}$ .

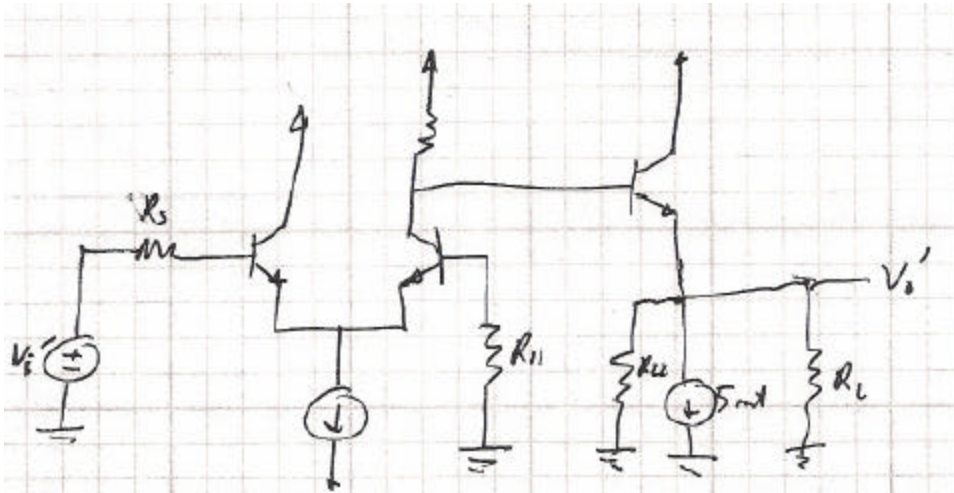


# FEEDBACK/STABILITY

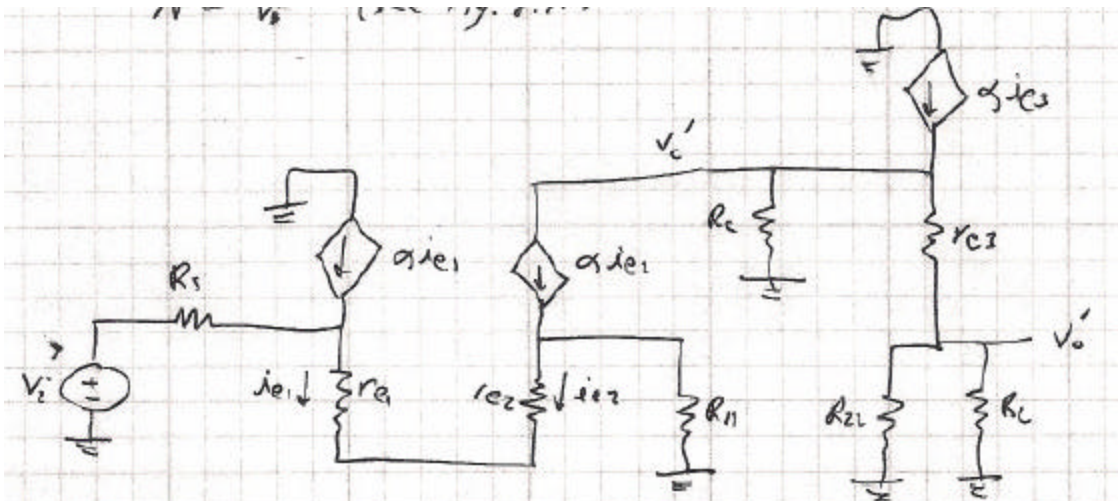


# FEEDBACK/STABILITY

A circuit:



$$A = V_o' / V_i$$



$$i_{e1} = -i_{e2} = \frac{V_i}{\frac{R_3}{\beta+1} + r_{e1} + r_{e2} + \frac{R_{11}}{\beta+1}}$$

$$V_c' = -\alpha i_{e2} \left\{ R_C \parallel \left[ (\beta+1) (r_{e3} + (R_{22} \parallel R_L)) \right] \right\}$$

$$\frac{V_c'}{V_i} = -\frac{\alpha [R_C \parallel (\beta+1) (r_{e3} + R_{22} \parallel R_L)]}{r_{e1} + r_{e2} + \frac{R_3 + R_{11}}{\beta+1}} = -\frac{0.99 (20k \parallel 169k)}{100\Omega + 108\Omega} = -85.1 \text{ V/V}$$

$$\frac{V_o'}{V_c'} = \frac{R_{22} \parallel R_L}{R_{22} \parallel R_L + r_{e3}} \approx 1$$

$$A = \frac{V_o'}{V_i} = -85.1 \text{ V/V}$$

# **FEEDBACK/STABILITY**

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