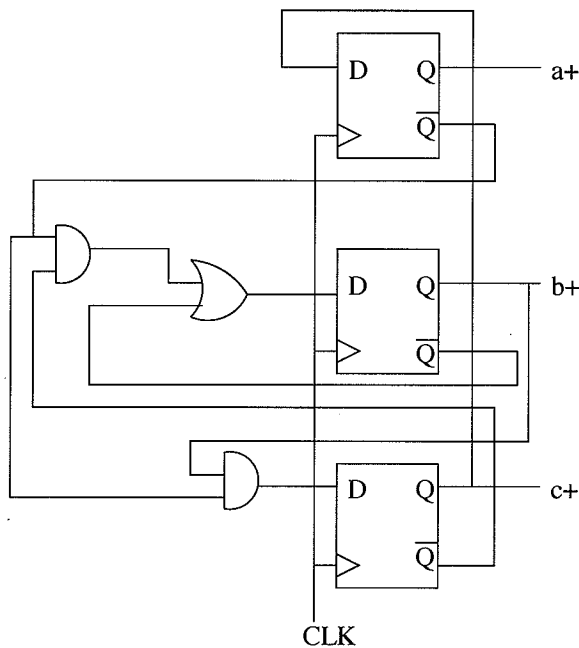


## Problem 1

From the State Transition Table, the expressions for the next-state bits can be written as,

$$\begin{aligned} a^+ &= c \\ b^+ &= \bar{b} + \bar{a} \cdot \bar{c} \\ c^+ &= \bar{a} \cdot b \end{aligned}$$

The counter is implemented using D-type flip-flops as shown in the figure below. The  $Q'$  output of the flip-flop is used to directly provide  $a'$ ,  $b'$  and  $c'$ . Inverters can also be used to provide these signals from the  $Q$  outputs.



## Problem 2

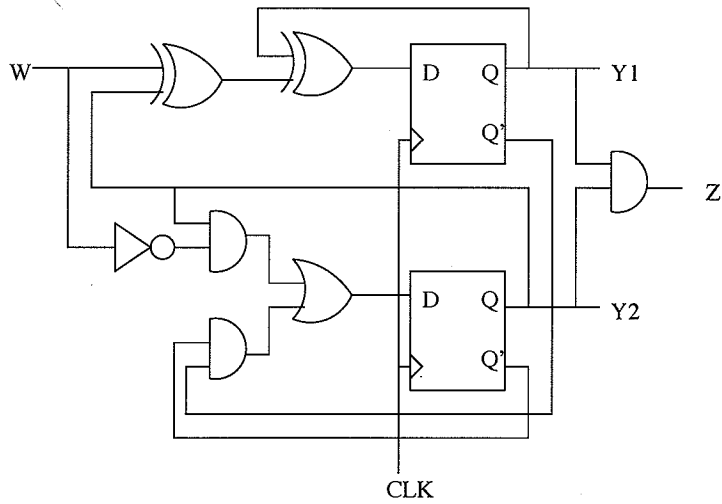
The expressions for the inputs of the flip-flops are:

$$\begin{aligned} Y_2 &= \bar{w} \cdot y_2 + \bar{y}_1 \cdot \bar{y}_2 \\ Y_1 &= w \oplus y_1 \oplus y_2 \end{aligned}$$

The output equation is

$$z = y_1 \cdot y_2$$

The output  $z$ , of this circuit depends on the state of the circuit only. This is a Moore machine. The circuit schematic is shown on the next page:



### Problem 3

The new next-state and output equations are found to be:

$$Y_2 = \overline{y_1} \cdot \overline{y_2} + w \cdot y_2$$

$$Y_1 = \overline{y_1} \cdot y_2 + w \cdot \overline{y_2}$$

$$z = y_1 \cdot \overline{y_2}$$

This code assignment seems to be a better choice, as compared to the previous one.

Table 1: State Transition Table

Present State $y_2 y_1$	Next State		Output $z$
	$w = 0$	$w = 1$	
	$Y_2 Y_1$	$Y_2 Y_1$	
1 1	0 0	0 1	0
1 0	1 0	1 1	0
0 0	0 1	1 1	0
0 1	0 0	1 0	1

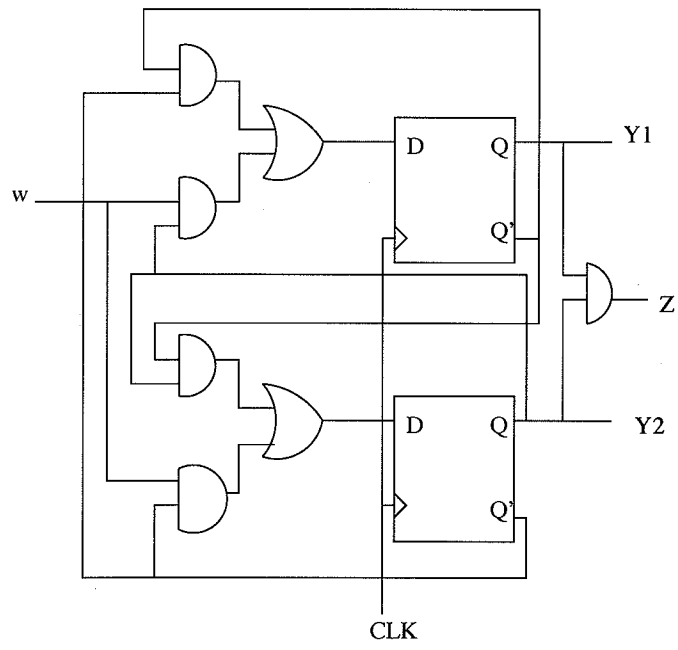


Figure 1: Circuit Diagram