Notes for Chapter 3: Waveguides

TM whees 26 TE Waves pp. 106-110  $(\sqrt{2} + k_c^2) H_z = 0$  (3.73)  $(\nabla^2 + k_c^2) E_z = 0$  (3.97) HZ = A ComTx com my - JBZ (3.81) Ez = Bm SimmTX sim nTy = 182 (3.100) From Eqs. 5.3 a - d, for TE/TM wars  $\frac{1}{H_t} = -\frac{1}{h_c^2} \nabla_t H_z - \frac{1}{h_c^2} \underbrace{\sum_{k=2}^{N} \nabla_t H_z} = \frac{1}{h_c^2} \underbrace{\sum_{k=2}^{N} \frac{1}{h_c^2}} \underbrace{\sum_{k=2}$ for the lowest cutoff frequency TM11m m=1, n=1 Hz = 0 for TE10 mode (the larest order Fraguery)  $H_z = A (\cos \frac{\pi x}{a} - j\beta^2)$ from Eqns. (1),(2) Ez=Businasina -jpz we can write the remaining comparents From Eqns. (1), (2)  $E_{y} = \frac{\int \omega \mu}{k_{c}} \frac{\partial H_{z}}{\partial x} = -\frac{\int \omega \mu \Delta h_{lo}}{\pi} Sin(\pi x) e (3.84 b) E_{x} E_{y} H_{x}, H_{y} from Eqns. (3)(4)$ Ex = - Jun 3H2 = 0  $H_{X} = -\frac{j\beta}{k^{2}} \frac{\partial H_{2}}{\partial x} - \frac{j\beta\alpha}{\pi} A_{10} - \frac{j\beta\alpha}{\alpha} e^{j\beta\alpha}$ 

Hy = Ex = Ez = 0

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ΣI	24 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	M, ; fol= Ce 1 + + 62 (3,103)	12- WZ (3.102)	Zm= 13 = 1 1-152) (3.104)	No= 10- (F/22)	4 }	TM = 2 Rs = 2 Rs + R = 2 Rs + R = 2 Rs + Rs = 2 R	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	
	fcm = \( \frac{\mathbb{R}}{\alpha} \frac{2 + \mathbb{R}}{\alpha} \\ \( \frac{2}{\alpha} \frac{2 + \mathbb{R}}{\alpha} \\  \( \frac{2}{\alpha} \frac{2 + \mathbb{R}}{\alpha} \\  \( \frac{2}{\alpha} \frac{2}{\alpha} \frac{2}{\alpha} \\  \]	TE, 15/2 Ce (3.85) TI	$\frac{1}{10^2 - w^2}$ (3.83)	TE = W/ = Me (3.86)	18= 16- 15- 11-(Fifz)	Po = ab (Ex) = ab (Emx)(3:32)	0 5	6/6 W2 686	3.6 al black 1-(fetz) MW
	Cut off framine for	Frymod mode	Probablion Constant B= W	Ware impedance Z TE = W/ = TE	Fride Wardingth Ag	Expression for power flow in the W G	At the west on Constraint of )	due to dielectric losses  dy metury,	Maxi rum porer handling Corbiting or porer that will

Table 2.6. Salient features of some commercially available rectangular waveguides.

EIA Designation WR( )	Inside Dimensions Inches	Cutoff Frequency c/2a GHz	Recommended Frequency Range for TE <sub>10</sub> Mode GHz	Theoretical CW Power Rating for Lowest to Highest Frequency MW
2300	23.000-11.500	0.256	0.32-0.49	153.0-212.0
2100	21.000-10.500	0.281	0.35-0.53	120.0-173.0
1800	18.000-9.000	0.328	0.41-0.625	93.4-131.9
1500	15.000-7.500	0.393	0.49-0.75	67.6-93.3
1150	11.500-5.750	0.513	0.64-0.96	35.0-53.8
975	9.750-4.875	0.605	0.75-1.12	27.0-38.5
770	7.700-3.850	0.766	0.96-1.45	17.2-24.1
650	6.500-3.250	0.908	1.12-1.70	11.9-17.2
510	5.100-2.550	1.157	1.45-2.20	7.5-10.7
430	4.300-2.150	1.372	1.70-2.60	5.2-7.5
340	3.400-1.700	1.736	2.20-3.30	3.1-4.5
284	2.840-1.340	2.078	2.60-3.95	2.2-3.2
229	2.290-1.145	2.577	3.30-4.90	1.6-2.2
187	1.872-0.872	3.152	3.95-5.85	1.4-2.0
159	1.590-0.795	3.711	4.90-7.05	0.79-1.0
137	1.372-0.622	4.301	5.85-8.20	0.56-0.71
112	1.122-0.497	5.259	7.05-10.00	0.35-0.46
90	0.900-0.400	6.557	8.20-12.40	0.20-0.29
75	0.750-0.375	7.868	10.00-15.00	0.17-0.23
62	0.622-0.311	9.486	12.40-18.00	0.12-0.16
51	0.510-0.255	11.574	15.00-22.00	0.080-0.107
42	0.420-0.170	14.047	18.00-26.50	0.043-0.058
34	0.340-0.170	17.328	22.00-33.00	0.034-0.048
28	0.280-0.140	21.081	26.50-40.00	0.022-0.031
22	0.224-0.112	26.342	33.00-50.00	0.014-0.020
19	0.188-0.094	31.357	40.00-60.00	0.011-0.015
15	0.148-0.074	39.863	50.00-75.00	0.0063-0.0090
12	0.122-0.061	48.350	60.00-90.00	0.0042-0.0060
10	0.100-0.050	59.010	75.00-110.00	0.0030-0.0041
8	0.080-0.040	73.840	90.00-140.00	0.0018-0.0026
7	0.065-0.0325	90.840	110.00-170.00	0.0012-0.0017
5	0.051-0.0255	115.750	140.00-220.00	0.00071-0.00107
4	0.043-0.0215	137.520	170.00-260.00	0.00052-0.00075
3	0.034-0.0170	173.280	220.00-325.00	0.00035-0.00047

Circular Wanequide

T E modes pp. 118-121

 $\left(\sqrt{2} + \mu_{5}^{2}\right) H^{5} = \left(\frac{9 b_{5}}{9^{5}} + \frac{b_{5}}{1} \frac{9b_{5}}{9} + \frac{b_{5}}{1} \frac{9b_{5}}{9}\right) H^{5} = 0 \qquad \left(\sqrt{2} + \mu_{5}^{2}\right) E^{5} = 0 \qquad (3.134)$ 

 $H_{2}(S, \phi) = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (3.121) || E_{2} = (A \sin n\phi + B \cos n\phi) J_{n}(k_{c}S) = (A \sin n\phi + B \cos n\phi) + (A \sin n\phi$ 

TM modes Pr. 122-126

Kz Fig. 3.11 Hz = 0

Similar to Eqs. (1), (2) on p. (20-1

 $H_t = -\frac{K_s}{16} L_{H_2}$  (5)

Et = jw/ 2x 7+Hz (6)

From Eqs. (3) (4) on p. (20-1

THE = - JUE SX TEZ (7)

 $TE_t = -\frac{\int B^2}{h^2} \nabla_t E_z \qquad (8)$ 

From p. 682 of the Text; for the transverse part of 7 (in Cylindrical coordinates)

 $\nabla = \hat{\beta} \frac{\partial}{\partial z} + \frac{\partial}{\partial z} \frac{\partial}{\partial z}$ 

 $Z_{TE} = \left| \frac{E_L}{H_L} \right| = \frac{WL}{B} = \sqrt{\frac{1 - \frac{E_L}{E_L}}{E_L}}$  (3.129)

 $Z_{TM} = \left| \frac{E_{+}}{H_{+}} \right| = \frac{B}{WE} = \sqrt{1 - \frac{f_{-}^{2}}{f_{-}^{2}}}$  (3.142)

From Egs (6) and (9)

Eφ = jw/ 3Hz = jw/ (Asin+B cosn+) J(hzs) = Exin + 1111

Exp is tangerial to the metallic wall at 9 = a

Eq=0 (a) 9= a

 $J'_{n}(k_{c}a) = 0$  (3.124)

The mth root of In is called

Prim (= kca = wcliteria)

These roots are tabulated in Table 3.3 on

p. 119 of the Text

From Egns. 3.121, (5) and (6), the rest of the fild emponers i.e. Eq, Eq, Hq, Hg

can be written. These are given as Eys. 3. 130 a-f in the Text

Ez is tongunial to the Ez=0@ S=a

In (kca) = In (knm) = 0
3.138

values of prim are tabulated in Troble 3.4 on p.122 of theText

From Egs. 3.135 and (7) (8) the vest of the fild components comber withen. The expressions for Eg, Ep, Hg, Hq are given as Egns. 3. 141 a - d of the Text.

Mosembany		TE,1 ; fel = 1.841 Ce TMO, ; fel = 2.405 Ce TE,1 ; fel = 2.405 Ce TMO, ; fel = 2.405 Ce	(1.15) 1.8416 < F < 0.95 3.0546 1.15 Fel < F < 0.95 Fel		Twe Ba2 1/	2/ = Rs / (fx) (fx + 1 )	$\frac{e'/e'}{2\beta} \frac{\omega^2}{\zeta^2} (3.28)$ $\frac{e''/e'}{2\beta} \frac{\omega^2}{\zeta^2} (3.28)$	2.7 (2a)2 1-(fe/fe) MW Where a is in inches.
1 1-1			8416 < F < 0.95		TWELAP (P(1-1) J(hz a) 4 k2	RELIATE	2 / (3.28)	2.7 (20,2 1-(42/2) MN where a is in inche.
	Cut off frequencies	Lovest Cutably promes made when promes	Recommuted bound for	Frish wordingth 1/3=2/1	Expression for porteflow	Attenuation Contract of the Same of which	dut to dielectric lossus	Maximum pour hunding Capability or pour there will come out brechadon

	Same Lower order was	3 2	of a circular Worguide 5 Text Pig. 3.14)		
Wave Type	TE11	TM <sub>01</sub>	TEO1	$^{ ext{IM}_{11}}$	TM <sub>02</sub>
Field distributions in cross-sectional plane, at plane of maximum transverse fields	Distributions below along this plane			Distributions below along this plane	
Field distributions along guide					
Field components present	Hz, Hr, He, Er, E		нг, т н , д	Ez. Er. Es. Hr. H.	Ez, Er, He
£	2.84 c. 2.mb	2.405 e	3,83 c. 2πb	3.83 c 2mb	5.52 c <sub>ε</sub> 2πb
Attenuation due to * imperfect conductors	027°0 + ((*)) ((1/2°)) = 11/2°45	$\frac{R_g}{b\eta_g} \frac{1}{[1-(f_g/f)^2]}$	N. (56,/6) <sup>2</sup> Sn. (1 - (6,/6) <sup>2</sup>	$\frac{R_g}{b^{1}e} \frac{1}{(1-(f_{Q}/f)^2)}$	Rs 1 (fc/f) 2
	Kg = 1/60	ne - 14/e - 377	γ <sub>ω</sub> /ε = 377//ε <sub>2</sub> otms	managed [Source:	S. Ramo [1].]

Fig. 4.19. Field patterns of some of the lowest frequency modes of a circular waveguide. [Source:

Table 2.8. Some standard circular waveguides. (All dimensions are in inches.)

	Inside Dimensions			Recommended Frequency Range		
EIA	Diameter	Tolerance	Roundness	TE <sub>11</sub> Mode,		
Designation		+ or -	Tolerance	GHz		
WC 992	9.915	.010	.010	0.803-1.10		
WC 847	8.470	.008	.008	0.939-1.29		
WC 724	7.235	.007	.007	1.10-1.51		
WC 618	6.181	.006	.006	1.29-1.76		
WC 528	5.280	.005	.005	1.51-2.07		
WC 451	4.511	.005	.005	1.76-2.42		
WC 385	3.853	.004	.005	2.07-2.83		
WC 329	3.292	.003	.003	2.42-3.31		
WC 281	2.812	.003	.003	2.83-3.88		
WC 240	2.403	.0025	.002	3.31-4.54		
WC 205	2.047	.002	.002	3.89-5.33		
WC 175	1.750	.0015	.0015	4.54-6.23		
WC 150	1.500	.0015	.0015	5.30-7.27		
WC 128	1.281	.0013	.0013	6.21-8.51		
WC 109	1.094	.001	.0011	7.27-9.97		
WC 94	0.938	.0009	.0009	8.49-11.6		
WC 80	0.797	.0008	.0008	9.97-13.7		
WC 69	0.688	.0007	.0007	11.6-15.9		
WC 59	0.594	.0006	.0006	13.4-18.4		
WC 50	0.500	.0005	.0005	15.9-21.8		
WC 44	0.438	.00045	.0004	18.2-24.9		
WC 38	0.375	.00038	.0004	21.2-29.1		
WC 33	0.328	.00033	.0003	24.3-33.2		
WC 28	0.281	.00028	.0001	28.3-38.8		
WC 25	0.250	.00025	.0001	31.8-43.6		
WC 22	0.219	.00025	.0001	36.4-49.8		
WC 19	0.188	.00025	.00007	42.4-58.1		
WC 17	0.172	.00025	.00007	46.3-63.5		
WC 14	0.141	.00025	.00005	56.6-77.5		
WC 13	0.125	.00025	.00005	63.5-87.2		
WC 11	0.109	.00025	.00005	72.7-99.7		
WC 9	0.094	.00025	.00005	84.8-116		

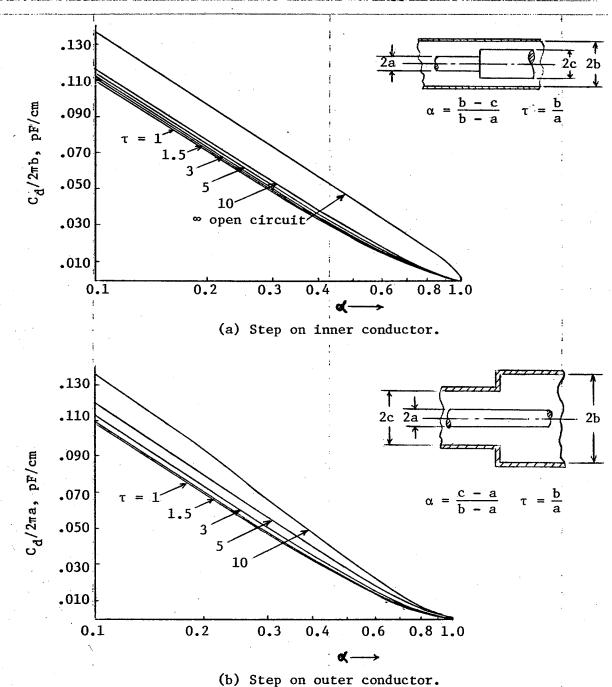
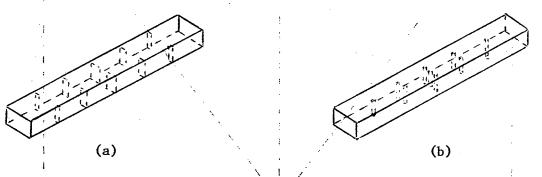
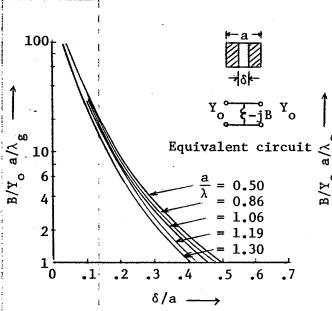


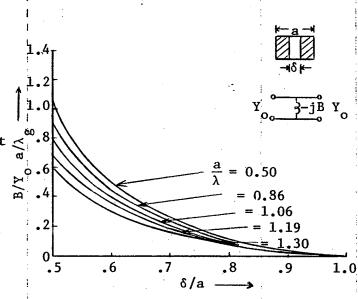
Fig. 8.21. Discontinuity capacitances for steps in a coaxial line. [Source: G. L. Matthaei, et  $\alpha l$ . [7] and J. R. Whinnery and H. W. Jamieson [8].]



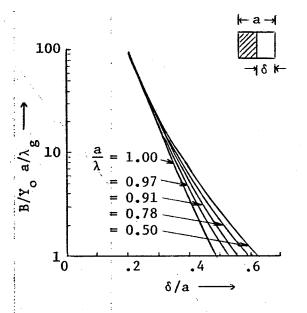
No text below this line 8.22. Some typical waveguide bandpass filters.



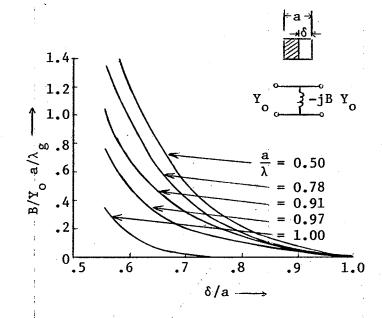
(a) Symmetrical inductive iris  $(\delta/a < 0.5)$ .



(b) Symmetrical inductive iris  $(\delta/a \ge 0.5)$ .



(c) Asymmetrical inductive iris (8/a < 0.6).



(d) Asymmetrical inductive iris  $(\delta/a > 0.5)$ .

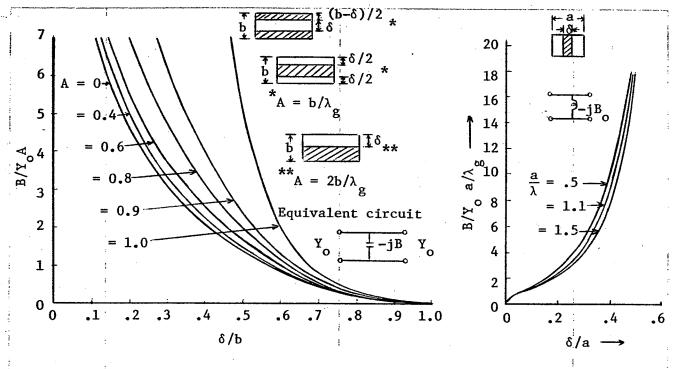
Fig. 8.23. Susceptance of discontinuities in a waveguide. [Source: G. L. Matthaei, et al. [7].]

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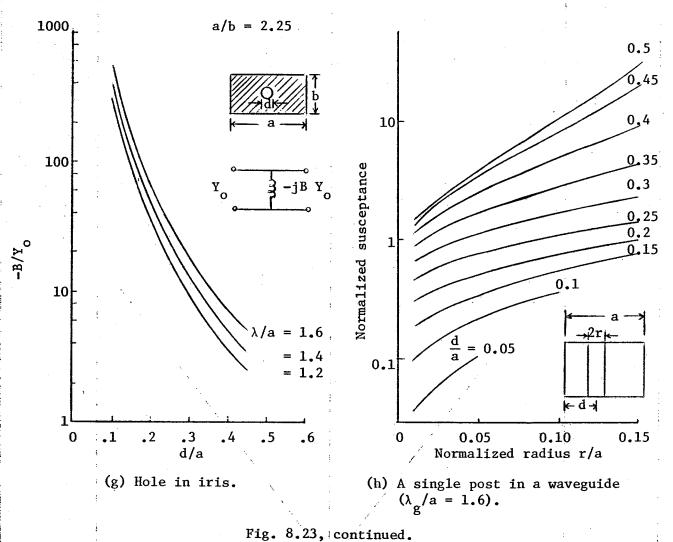






(e) Capacitive irises.

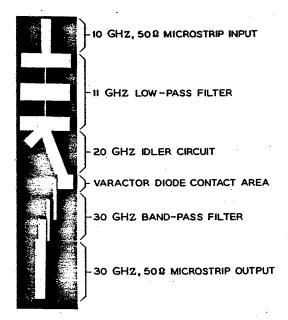
(f) Centered thin vane.



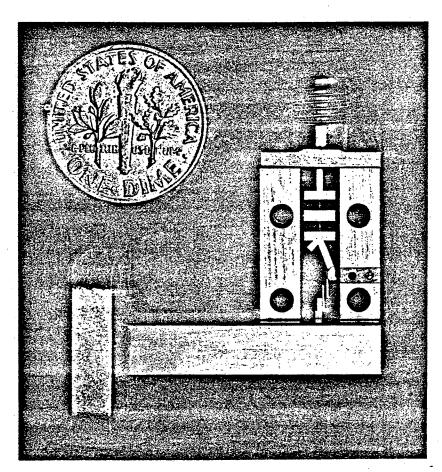
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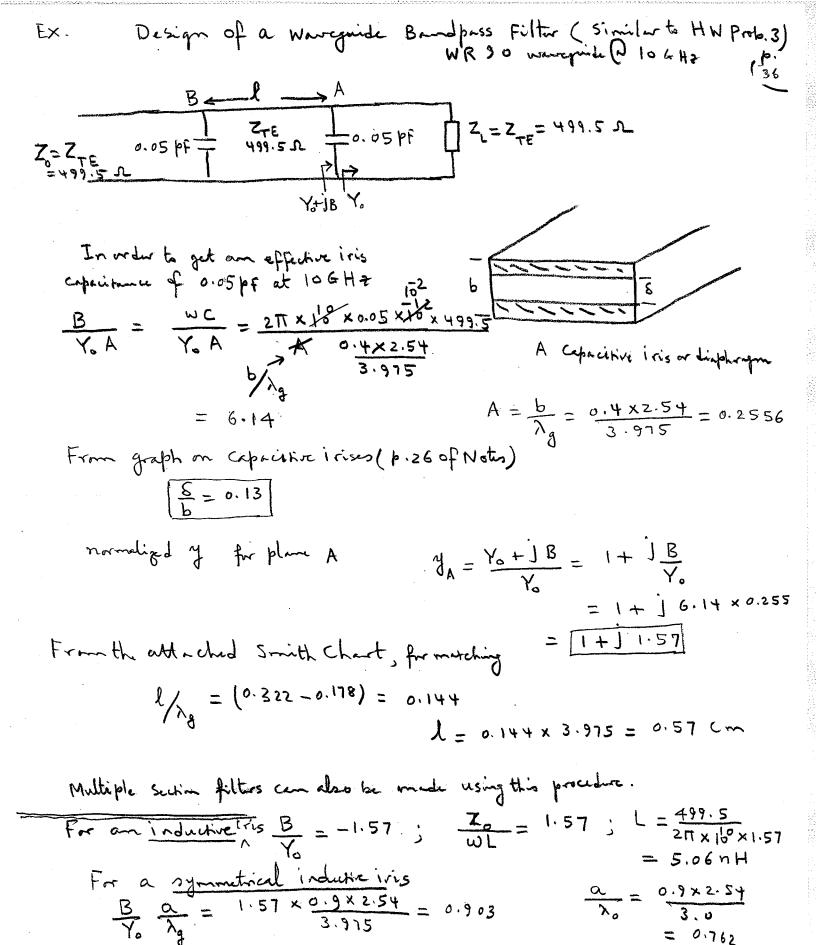


(a) Conductor pattern on silica substrate

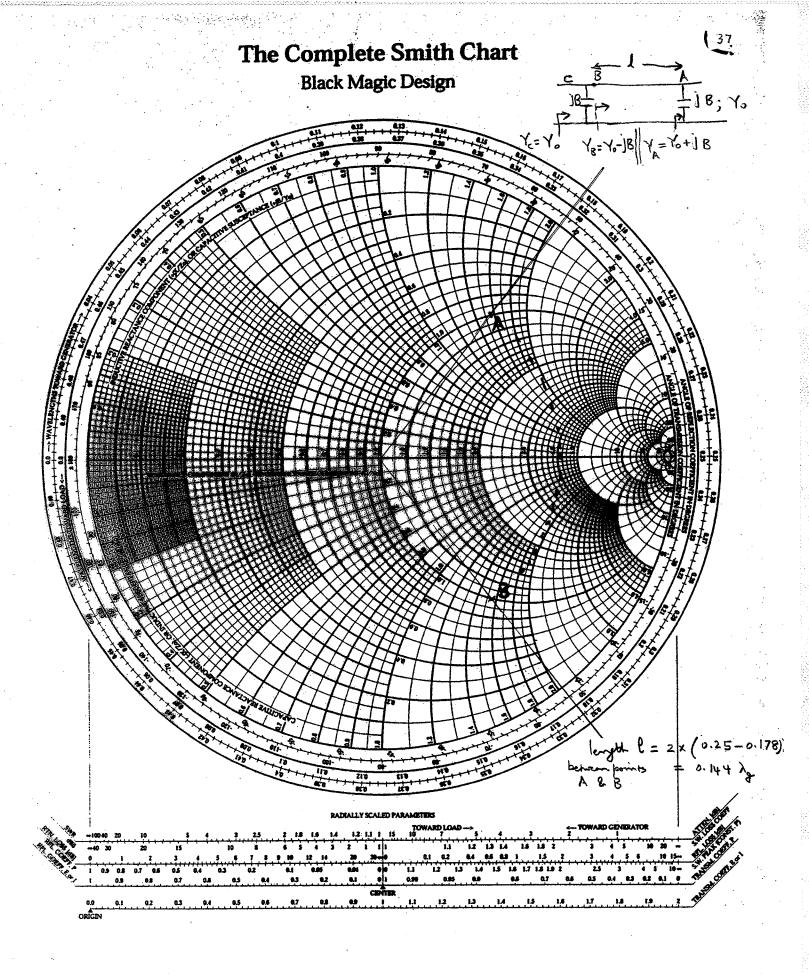


(b) The physical layout including the coax to microstrip and microstrip to WR 28 waveguide transitions

Fig. 8.24. An integrated circuit 10-30 GHz harmonic generator. [Source: M. V. Schneider and W. W. Snell, Jr. [9].]



From graphon 6.25  $\frac{5}{a} \sim 0.51$  for  $\frac{a}{\lambda} = 0.762$ 



Chapter 3 - Section 3.1 ( pr. 92 - 97)

From

O. P. Gandhi - Microsove Engineering and Applications, Pergamon Press, 1980. ( see also postor-110 Pozar Text)

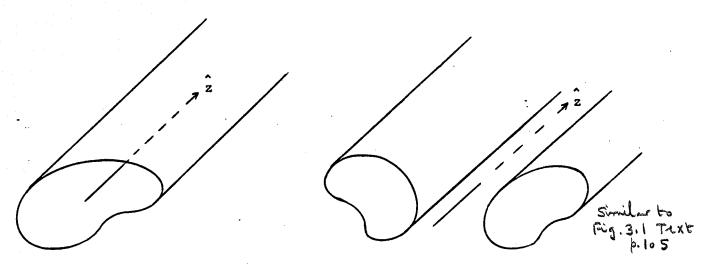
b. 105 Text by Pozar

2.2 Unified Theory -- Wave Propagation in a General "Cylindrical" Waveguide

A general [1] cylindrical waveguiding system is an arrangement of conductor/s, hollow or solid, which have the unchanging cross section as a function of z, which is the direction of propagation of energy. Some typical schematics of a general cylindrical waveguide are illustrated in Fig. 2.1.

From the definition of the general cylindrical waveguide, it can be seen that all waveguiding systems fit this definition. A circular waveguide, a rectangular waveguide, elliptical and triangular waveguides, coaxial line, parallel plate striplines, etc., have the same cross-sectional shape at various values of z and are consequently general cylindrical waveguides.

In most textbooks the above waveguiding systems are treated separately, equations of wave propagation solved, and the field patterns of various possible modes are derived. In this text we shall derive certain general unifying relationships in a general cylindrical waveguiding system since these are not that complicated



- (a) A single hollow conducting tube of arbitrary cross section that maintains the same shape at all values of z.
- (b) Two or more solid conductors of arbitrary cross section parallel to one another either side by side or one enclosing the others.

Fig. 2.1. Some typical general cylindrical waveguiding systems.

either to derive mathematically or to comprehend physically. The advantage we shall gain by following this approach, unlike that of most senior level texts, is that these general relationships, once derived, would be applied to the various systems to derive the possible modes without need for repetitious rederivation for each geometry.

A waveguide mode is a unique arrangement of the electric and magnetic fields propagating in the z-direction that satisfies all the Maxwell's equations (Appendix A) and the boundary conditions imposed by the geometry of the conductor/s of the transmission system (line). In other words, the various waveguide modes are different possible propagating solutions of the Maxwell's equations subject to the boundary conditions of the system. Having obtained these solutions by solving the boundary value problem, it will be necessary to launch the so-derived unique arrangement of the electric and magnetic fields on the system to assure the excitation of a single waveguide mode.

The various waveguide modes possible in waveguides may be categorized in one of the four possible categories:

- a. Transverse ElectroMagnetic mode or TEM mode.

  In this mode both the electric and magnetic fields are purely transverse to the direction of propagation and consequently have no z-directed components; i.e., both  $\rm E_z$  and  $\rm H_z$  are zero.
- b. Transverse Electric mode or  $\overline{\text{TE}}$  mode. In this mode only the electric field is purely transverse to the

direction of propagation and the magnetic field is not purely transverse; i.e.,  $E_z = 0$ ,  $H_z \neq 0$ .

c. Transverse Magnetic mode or TM mode.

In this mode only the magnetic field is purely transverse to the direction of propagation while the electric field is not purely transverse and therefore would have a component in the direction of propagation; i.e.,  $H_z = 0$ ,  $E_z \neq 0$ .

d. Hybrid modes or HE modes.

These modes have neither the electric nor the magnetic field purely transverse to the direction of propagation; i.e., both  $\vec{E}$  and  $\vec{H}$  have components along the direction of propagation;  $E_z \neq 0$ ,  $H_z \neq 0$ .

#### 2.3 Field Relationships in a General "Cylindrical" Waveguide

The schematic of a general "cylindrical" waveguide is shown in Fig. 2.1. From Maxwell's equations (derived in Appendix A):

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} = -j\omega\mu \vec{H}$$
 (2.1) i.41 \(\text{T-ext}\)

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} = j\omega \epsilon \vec{E}$$
 (2.2)

$$\nabla \cdot \overrightarrow{B} = 0 \tag{2.3}$$

$$\nabla \cdot \overrightarrow{D} = 0 \tag{2.4}$$

Taking the curl of Eq. 2.1, we obtain the wave equation for E in a general coordinate system:

$$\nabla \times \nabla \times \stackrel{\rightarrow}{E} = -j\omega\mu \quad \nabla \times \stackrel{\rightarrow}{H} = \omega^2 \mu \epsilon \stackrel{\rightarrow}{E} \equiv k_{\epsilon}^{2} \stackrel{\rightarrow}{E}$$
 (2.5)

where  $k_{\epsilon}$  denotes  $\omega \sqrt{\mu\epsilon}$  which is  $\omega / c_{\epsilon}$  with  $c_{\epsilon} = 1/\sqrt{\mu\epsilon}$  being the velocity of light in the dielectric medium filling the waveguide.  $k_{\epsilon}$ , in other words, is the propagation constant of electromagnetic waves in the filler medium of infinite cross section.

From vector calculus (see Appendix B) it can be shown that

$$\nabla \times \nabla \times \overrightarrow{E} = \nabla(\nabla \cdot \overrightarrow{E}) - \nabla^{2}\overrightarrow{E}$$
 (2.6)

in the Cartesian system or for the z-component of  $\vec{E}$  in the cylindrical system. The exception for the z-component is because it is indistinguishable between the Cartesian system (where Eq. 2.6 is valid) and the cylindrical system.

Since  $\nabla \cdot \stackrel{\rightarrow}{E} \equiv 0$  from Eq. 2.4, the wave equation for the z-component  $E_z$  for our general waveguide can be written as

$$\nabla^2 E_z + k_\varepsilon^2 E_z = 0 \tag{2.7}$$

By starting with the curl of Eq. 2.2 and proceeding in a similar manner as above, the wave equation for the z-component of magnetic field can be obtained as

$$\nabla^2 H_z + k_z^2 H_z = 0 (2.8) \frac{1+3}{1-4}$$

Solving the wave equations (2.7) and (2.8) subject to the boundary conditions of the waveguide, we can, in principle, obtain the solutions for  $E_z$  and  $H_z$ . It will now be our attempt to find the transverse (remaining) components of the electric and magnetic fields  $\vec{E}_t$  and  $\vec{H}_t$  so that  $\vec{E}$  and  $\vec{H}$  are completely known. It should be mentioned at this stage that  $\vec{E}_t$  and  $\vec{H}_t$  represent two components each in the transverse plane.

The operator del  $\nabla$  similarly is also written as a sum of the z-directed part and the transverse part; i.e.,

$$\vec{\nabla} \equiv \vec{\nabla}_z + \vec{\nabla}_z \tag{2.9}$$

Once again  $\overrightarrow{\nabla}_{t}$  represents two components as may be seen by the illustrative examples of the Cartesian and cylindrical coordinate systems. In Cartesian coordinates,

$$\vec{\nabla} = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} + \hat{z} \frac{\partial}{\partial z} \equiv \vec{\nabla}_{t} + \vec{\nabla}_{z}$$
 (2.10)

where

$$\vec{\nabla}_{t} = \hat{x} \frac{\partial}{\partial x} + \hat{y} \frac{\partial}{\partial y} \text{ and } \vec{\nabla}_{z} \equiv \hat{z} \frac{\partial}{\partial z}$$
 (2.11)

In cylindrical coordinates,

$$\vec{\nabla} = \hat{\mathbf{r}} \frac{\partial}{\partial \mathbf{r}} + \hat{\boldsymbol{\theta}} \frac{1}{\mathbf{r}} \frac{\partial}{\partial \boldsymbol{\theta}} + \hat{\mathbf{z}} \frac{\partial}{\partial \mathbf{z}} \equiv \vec{\nabla}_{\mathbf{t}} + \vec{\nabla}_{\mathbf{z}}$$
 (2.12)

and

$$\vec{\nabla}_{t} = \hat{r} \frac{\partial}{\partial r} + \hat{\theta} \frac{1}{r} \frac{\partial}{\partial \theta}$$
 (2.13)

Equating the transverse components on both sides of Eq. 2.1:

$$\vec{\nabla} \times \vec{E} \Big|_{t} = (\vec{\nabla}_{z} + \vec{\nabla}_{t}) \times (\vec{E}_{z} + \vec{E}_{t}) \Big|_{t}$$

$$= \vec{\nabla}_{z} \times \vec{E}_{t} + \vec{\nabla}_{t} \times \vec{E}_{z} = -j\omega\mu\hat{H}_{t}$$
(2.14)

Similarly, from Eq. 2.2,

$$\vec{\nabla}_{z} \times \vec{H}_{t} + \vec{\nabla}_{t} \times \vec{H}_{z} = j\omega \epsilon \vec{E}_{t}$$
 (2.15)

Cross multiplying both sides of Eq. 2.15 by  $\overrightarrow{\nabla}_z$ , we obtain:

$$\vec{\nabla}_{z} \times (\vec{\nabla}_{z} \times \vec{H}_{t}) + \vec{\nabla}_{z} \times (\vec{\nabla}_{t} \times \vec{H}_{z}) = j\omega \epsilon \vec{\nabla}_{z} \times \vec{E}_{t}$$
 (2.16)

Making use of the vector relationship (Appendix B)

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - (\vec{A} \cdot \vec{B})\vec{C}$$

$$(2.17) = \vec{A} \cdot \vec{C}$$

we can write

$$\vec{\nabla}_z \times (\vec{\nabla}_z \times \vec{H}_t) = \vec{\nabla}_z (\vec{\nabla}_z \cdot \vec{H}_t)^0 - (\vec{\nabla}_z \cdot \vec{\nabla}_z) \vec{H}_t$$
 (2.18)

$$\vec{\nabla}_{z} \times (\vec{\nabla}_{t} \times \vec{H}_{z}) = \vec{\nabla}_{t} (\vec{\nabla}_{z} \cdot \vec{H}_{z}) - (\vec{\nabla}_{z} \cdot \vec{H}_{z})$$
(2.19)

Since in waveguide transmission we are interested in solutions capable of propagation along the length of the guide, we are searching for solutions of  $\vec{E}$  and  $\vec{H}$  that vary as  $e^{-j\beta z}$ , in which case  $\vec{\nabla}_z = \hat{z} \partial/\partial z = -j\beta \hat{z}$  and Eq. 2.16 can be written as:

$$\beta^{2} \stackrel{\rightarrow}{H}_{t} - j\beta \stackrel{\rightarrow}{\nabla}_{t} H_{z} = j\omega \epsilon \stackrel{\rightarrow}{\nabla}_{z} \times \stackrel{\rightarrow}{E}_{t}$$
 (2.20)

Upon substituting for  $\vec{\nabla}_z \times \vec{E}_t = -j\omega\mu \vec{H}_t - \vec{\nabla}_t \times \vec{E}_z$  from Eq. 2.14, the right side of Eq. 2.20 is written as:

$$j\omega\varepsilon \left[ -j\omega\mu \overset{\rightarrow}{H}_{t} - \overset{\rightarrow}{\nabla}_{t} \times \overset{\rightarrow}{E}_{z} \right] = k_{\varepsilon}^{2}\overset{\rightarrow}{H}_{t} - j\omega\varepsilon \overset{\rightarrow}{\nabla}_{t} \times \overset{\rightarrow}{E}_{z}$$

$$= k_{\varepsilon}^{2}\overset{\rightarrow}{H}_{t} + j\omega\varepsilon \overset{\widehat{z}}{z} \times \overset{\rightarrow}{\nabla}_{t}^{E}_{z} \qquad (2.21)$$

Upon rearranging terms, Eq. 2.20 is written as:

$$\left| (k_{\varepsilon}^{2} - \beta^{2}) \overrightarrow{H}_{t} = -j\omega\varepsilon \widehat{z} \times \overrightarrow{\nabla}_{t} E_{z} - j\beta \overrightarrow{\nabla}_{t} H_{z} \right|$$
 (2.22)

An equation for  $\overrightarrow{E}_t$  is similarly derived by cross multiplying Eq. 2.14 with  $\overrightarrow{\nabla}_z$ :

$$\left[ \left( k_{\varepsilon}^{2} - \beta^{2} \right) \vec{E}_{t} = +j\omega_{\mu} \hat{z} \times \vec{\nabla}_{t} H_{z} - j\beta \vec{\nabla}_{t} E_{z} \right]$$
 (2.23)

Equations 2.22 and 2.23 are important general equations that allow the evaluation of the transverse components  $\vec{E}_t$  and  $\vec{H}_t$  once  $E_z$  and  $H_z$  are known (from the solutions of Eq. 2.7 and Eq. 2.8 subject to the boundary conditions).

### <u>Transverse ElectroMagnetic or TEM Modes (E<sub>z</sub> = 0, H<sub>z</sub> = 0)</u>

Equations 2.22 and 2.23 are not too useful for TEM modes since for these modes the right sides of the equations are zero, and that means that either  $\dot{E}_t = 0$ ,  $\dot{H}_t = 0$  which would imply zero fields, which is a trivial solution, or that  $\beta = k_c$ . The latter solution is a powerful relationship, which means that for TEM modes the waves propagate at the velocity corresponding to that of unbounded electromagnetic waves in the filler medium.

Other than this important result, Eqs. 2.22 and 2.23 are incapable of allowing us the calculation of  $\dot{E}_t$  and  $\dot{H}_t$  for which an alternative approach will be developed in the next Section 2.4.

# <u>Transverse</u> <u>Electric</u> or <u>TE</u> Modes ( $E_z = 0$ , $H_z \neq 0$ )

For these modes  $E_z = 0$ ;  $H_z$  is obtained from the solution of Eq. 2.8, and the figure parameters (2.22) and (2.23) can be simplified to:

$$H_{X} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ a}$$

$$H_{X} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ b}$$

$$H_{Z} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ b}$$

$$H_{Z} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ b}$$

$$H_{Z} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ b}$$

$$H_{Z} = -\frac{j\beta}{kz^{2}} \frac{\partial H_{z}}{\partial X} \quad 3.19 \text{ b}$$

$$E_{x} = \frac{\omega}{\beta} H_{z} = -\frac{1}{3} \frac{\partial H_{z}}{\partial z} \frac{\partial H_{z}}{$$

From Eqs. 2.24 and 2.25, it can be seen that the transverse fields  $\vec{E}_t$  and  $\vec{H}_t$  are at right angles to one another at all points in the transverse plane. Furthermore  $\vec{E}_t$ ,  $\vec{H}_t$ , and  $\hat{z}$  are oriented such that they form a right-handed coordinate system  $(\vec{E}_t || (\vec{H}_t \times \hat{z}), \hat{z} || (\vec{E}_t \times \vec{H}_t)$ , etc.). Also, the magnitude of  $\vec{E}_t$  at all points is  $(\omega \mu / \beta)$  times that of  $\vec{H}_t$ . The ratio of the magnitudes of  $\vec{E}_t$  and  $\vec{H}_t$ , having the dimensions of the impedance, is called the wave impedance.

The TE modes wave impedance  $\boldsymbol{Z}_{\text{TE}}$  is therefore:

$$Z_{TE} = \frac{\omega \mu}{\beta} = 377 \frac{\lambda}{\lambda_0} \text{ ohms}$$

$$(2.26)$$

$$(2.26)$$

where  $\lambda_g$  (=  $2\pi/\beta$ ) and  $\lambda_o$  are the guide and free-space wavelengths; respectively.

A physical interpretation of the guide wavelength  $\lambda_{\rm g}$  (=  $2\pi/\beta$ ) is that at any given instant of time, the fields are  $2\pi$  out of phase and consequently repetitive at points that are axially separated by  $\lambda_{\rm g}$ .

Since at the metallic waveguide walls only tangential components of magnetic field and normal component of electric field can exist, that means that at the waveguide walls the normal component of Eq. 2.24 should be zero. Denoting by n the unit vector normal to the waveguide wall pointing out of the metal,

$$\vec{H}_{n} = \hat{n} \times \vec{H}_{t} = \frac{-j\beta}{k_{\varepsilon}^{2} - \beta^{2}} \hat{n} \cdot \vec{\nabla}_{t} H_{z} = -\frac{j\beta}{k_{\varepsilon}^{2} - \beta^{2}} \frac{\partial H_{z}}{\partial n} = 0$$
 (2.27)

at the waveguide walls, or simply

$$\partial H_z/\partial n = 0 \tag{2.28}$$

at the waveguide walls. This is an important boundary condition that is needed to obtain the solution for  $H_z$  from Eq. 2.8. After solving for  $H_z$ ,  $\overrightarrow{H}_t$  and  $\overrightarrow{E}_t$  are obtained from Eqs. 2.24 and 2.25 and the fields are then completely known for a given TE mode.

### <u>Transverse Magnetic or <u>TM</u> Modes ( $H_z = 0$ , $E_z \neq 0$ )</u>

For these modes  $H_z = 0$  and  $E_z$  is obtained from the solution of Eq. 2.7 subject to the boundary condition that  $\mathbf{E}_{\mathbf{z}}$  being tangential electric field is zero at the metallic waveguide walls. Having obtained a solution for  ${ t E}_{f z}$  in this manner, the remaining field components are obtained from the simplified versions of the general equations (2.22) and (2.23); i.e.,

$$E_{x} = -\frac{1}{h_{c}^{2}} \frac{\partial E_{z}}{\partial x} \qquad 3.23(C)$$

$$E_{y} = -\frac{1}{h_{c}^{2}} \frac{\partial E_{z}}{\partial y} \qquad 3.23(d)$$

$$H_{x} = \frac{1}{h_{c}^{2}} \frac{\partial E_{z}}{\partial y} \qquad 3.23(d)$$

$$H_{z} = \frac{1}{h_{c}^{2}} \frac{\partial E_{z}}{\partial y} \qquad 3.23(d)$$

$$H_{X} = \frac{1}{k_{c}^{2}} \xrightarrow{\delta E_{2}} 3.23(a)$$

$$H_{z} = -\frac{1}{k_{c}^{2}} \xrightarrow{\delta E_{2}} 3.23(b)$$

$$H_{z} = \frac{-j\omega\varepsilon}{k_{c}^{2} - \beta^{2}} \hat{z} \times \nabla_{z} E_{z} = \frac{\omega\varepsilon}{\beta} \hat{z} \times E_{z}$$

$$(2.30)$$

As in the case of the TE modes, for TM modes too, the fields  $\overrightarrow{E}_t$  and  $\overrightarrow{H}_t$  are at right angles at all points in the transverse plane, with  $\vec{E}_t$ ,  $\vec{H}_t$ , and  $\hat{z}$  forming a right-handed coordinate system. The  $\overrightarrow{E}_t$  and  $\overrightarrow{H}_t$  amplitudes are related by the factor  $\beta/\omega\epsilon$  and the wave impedance  $Z_{TM}$ , being the ratio of the magnitudes of  $\dot{\overline{E}}_{\mathsf{t}}$ and  $\hat{H}_{\downarrow}$ , is given by:

$$Z_{TM} = \frac{\beta}{\omega \varepsilon} = 377 \frac{\lambda_0}{\lambda_g} \quad \text{ohms}$$
 (2.31)

#### HE or Hybrid Modes

For these modes the complete equations (2.22) and (2.23) are to be used.

#### 2.4 TEM Modes in Waveguiding Systems

For such modes, by definition, the electric and magnetic fields are purely transverse to the direction of propagation. In Section 2.3 we showed that such modes propagate with a propagation constant  $k_{\epsilon}$ , i.e., with the phase velocity corresponding to the velocity of unbounded electromagnetic waves  $c_{\epsilon}$  in the filler medium. An interesting feature of these waves is that they can be excited down to zero frequency while, as will be shown later, the other modes, namely TE, TM, or HE, can only be excited above certain frequencies, called the cutoff frequencies.

It will be shown in this section that two or more conductors are, however, needed in the transmission line to excite TEM modes which therefore would make it impossible to excite TEM modes in single conductor systems such as the rectangular and circular waveguides and hollow pipes of other cross-sectional shape such as elliptical, wedge-shaped, etc.

Since the electric and magnetic fields  $\vec{E}_t$  and  $\vec{H}_t$  cannot be derived from the general equations (2.22) and (2.23), we start from the basic Maxwell's equations (from Appendix A):

$$\nabla \times \vec{H} = j\omega \varepsilon \vec{E}$$
 (2.32)

$$\nabla \times \overrightarrow{E} = -j\omega\mu \overrightarrow{H}$$
 (2.33)

$$\nabla \cdot \overrightarrow{B} = 0 \tag{2.34}$$

$$\nabla \cdot \vec{D} = 0 \tag{2.35}$$

From Eq. 2.34,  $\vec{B}$  can be expressed as curl of a vector  $\vec{A}$  which is called the magnetic vector potential.

$$\vec{B} = \vec{\nabla} \times \vec{A} = (\vec{\nabla}_t + \vec{\nabla}_z) \times (\vec{A}_t + \vec{A}_z)$$
 (2.36)

From Eq. 2.36 the z-component and the transverse components of  $\overrightarrow{B}$  can be written:

$$\vec{B}_z = \vec{\nabla}_t \times \vec{A}_t \tag{2.37}$$

$$\vec{B}_{t} = \vec{\nabla}_{z} \times \vec{A}_{t} + \vec{\nabla}_{t} \times \vec{A}_{z}$$
 (2.38)

Now, since for TEM fields,  $\vec{B}_z \equiv 0$ , that means from Eq. 2.37 that  $\vec{A}_t \equiv 0$ ; in other words, for TEM fields, the magnetic vector potential  $\vec{A}$  is purely z-directed,  $\vec{A} \equiv \vec{A}_z$ .

From Eq. 2.33, we can write,

$$\nabla \times \left( \vec{E} + j\omega \vec{A}_z \right) = 0 \tag{2.39}$$

The term  $\vec{E} + j\omega \vec{A}_Z$  within the parentheses can, therefore, be written as the gradient of a scalar function  $\psi$  since  $\nabla \times (-\nabla \psi) \equiv 0$ . Hence,

$$\vec{E} = -\vec{\nabla}\psi - j\omega \vec{A}_{z} \tag{2.40}$$

Now since  $\overrightarrow{E}_z \equiv 0$  for TEM waves, from Eq. 2.40,

$$-\vec{\nabla}_z \psi - j \omega \vec{A}_z = j k_\varepsilon \psi \hat{z} - j \omega A_z \hat{z} = 0$$
 (2.41)

or

$$\psi = \frac{\omega}{k} A_z \tag{2.42}$$

In terms of  $\psi$  therefore, from Eq. 2.40,

$$\vec{E}_{t} = -\vec{\nabla}_{t} \psi \tag{2.43}$$

from Eq. 2.38,

$$\vec{H}_{t} = \frac{1}{\mu_{o}} \vec{\nabla}_{t} \times \vec{A}_{z} = -\frac{k}{\omega \mu_{o}} \hat{z} \times \vec{\nabla}_{t} \psi = \frac{1}{\eta_{\varepsilon}} \hat{z} \times \vec{E}_{t}$$
(2.44)

where  $\eta_{\varepsilon} = \sqrt{\mu_0/\varepsilon} = 377/\sqrt{\varepsilon_r}$  is the intrinsic impedance of the filler dielectric. As in the case of TE and TM waves, so also here we can see that the transverse electric and magnetic fields are at all points mutually perpendicular and  $\dot{E}_t$ ,  $\dot{H}_t$ , and  $\dot{z}$  form a right-handed coordinate system.

From Eq. 2.35,

$$\nabla \cdot \overrightarrow{D} = \varepsilon \nabla \cdot \overrightarrow{E}_{t} = -\varepsilon \nabla_{t}^{2} \psi = 0 \qquad (2.45)$$

From Eq. 2.45 we can see that  $\psi$  satisfies the two-dimensional version of the Laplace's equation  $\left(\nabla^2_t \psi = 0\right)$  which is the equation governing the electrostatic fields. Once  $\psi$  is determined from Eq. 2.45, the electric and magnetic fields can be written from Eqs. 2.43 and 2.44. The fields so obtained are then multiplied by

e to represent the time-varying propagating fields rather than the electrostatic fields that Eqs. 2.43-2.45 would otherwise represent. Therefore, the TEM fields can be visualized as the time-varying, e jkez propagating fields of the same variation in the cross-sectional plane as the electrostatic fields. It is obvious then that if TEM modes are to exist in a transmission system, electrostatic fields should be possible in that system. Single conductor systems being electrostatically equipotential are incapable of producing electrostatic field variations in the cross-sectional plane, hence forbidding the existence of TEM waves in such systems.

The wave impedance  $Z_{\overline{\text{TEM}}}$  is defined, as before, by the ratio of the magnitudes of the transverse electric and magnetic fields. From Eqs. 2.43 and 2.44,

$$Z_{\text{TEM}} = \frac{\left|\vec{E}_{t}\right|}{\left|\vec{H}_{t}\right|} = \eta_{\varepsilon} = \frac{377}{\sqrt{\varepsilon_{r}}} \text{ ohms}$$
 (2.46)

A more important quantity in TEM modes is the so-called characteristic impedance Z of the transmission line. This is the equivalent impedance that will absorb, from the source, the power P that the transmission line is propagating while producing the RF potential  $(\psi_2 - \psi_1)$  between its terminals corresponding to the RF potential between the two conductors of the transmission line.

Consequently, the characteristic impedance, Z, is given by:

$$Z_{2} = \frac{(\psi_{2} - \psi_{1})^{2}}{2P}$$
 (2.47)

For multiconductor transmission lines where different potential differences can be established between the various conductors, it is obvious that more than one TEM mode is possible.

## 2.5 Attenuation in General "Cylindrical" Waveguides

#### Due to Conductor Losses

The propagation of fields associated with the waveguide mode induces surface currents on the metallic waveguide walls. The currents on the wall surfaces are due to the tangential components of the magnetic field and are given by:

$$\vec{J} = \hat{n} \times \vec{H} \tag{2.48}$$

where n is the unit vector normal to the waveguide wall directed towards the