Ex: The circuit shown below is the small-signal model of an emitter follower incorporating an npn transistor (modeled by  $R_b$  and source  $\beta i_b$ ). The input voltage in practice would be something like a music waveform. The capacitor couples the input to the input of the transistor, which is biased by  $R_1$  and  $R_2$  and a DC power supply that disappears in the small-signal model, (think superposition). The *L* represents a speaker coil (which has an impedance value that will look familiar to those who have worked with audio systems).



**Note:**  $v_{in}(t) = 300 \cos(800t) \,\mathrm{mV}$ 

a) The value of  $R_b$  for the small-signal model is found by linearizing the currentversus-voltage curve for a diode in the npn transistor. The equation for the diode is as follows:

$$i_D = I_0 \left( e^{v_D/v_T} - 1 \right)$$

where  $I_0 = 0.010$  pA is the reverse saturation current of the diode

 $v_{\rm T} = kT/q = 26 \text{ mV}$  at room temperature

 $v_D$  = voltage across diode

 $i_D$  = current in diode

The above values are deduced from a data sheet for a standard 1N914 diode (rather than an npn transistor). The URL for the diode data is <u>http://www.mouser.com/ds/2/149/1N914-192459.pdf</u>.

The formula for  $R_b$  is based on the slope of the nonlinear diode equation at an operating point of 0.7 V across the diode:

$$R_{\rm b} = \frac{1}{\frac{di_D}{dv_D}}\Big|_{v_D = 0.70\,\rm V}$$

Using the above formula, find the value of  $R_{\rm b}$ .

- b) Draw the frequency-domain circuit diagram (with numerical values for impedances and phasors [except the dependent source which is a multiple of the dependent variable]) for the circuit shown above.
- **SOL'N:** a) The derivative is just the derivative of an exponential function, since the -1 is a constant with respect to  $v_D$ .

$$\left. \frac{di_D}{dv_D} \right|_{v_D = 0.70 \text{ V}} = \frac{dI_0 \left( e^{v_D / v_T} - 1 \right)}{dv_D} \right|_{v_D = 0.70 \text{ V}}$$

The derivative must be found before plugging in numbers. Otherwise, we would be differentiating a number and would get zero. Our derivative is like finding d/dx of  $Ae^{ax}$ , which gives  $aAe^{ax}$ .

$$\frac{di_D}{dv_D}\Big|_{v_D=0.70\,\mathrm{V}} = \frac{1}{v_T} I_0 e^{v_D/v_T} \Big|_{v_D=0.70\,\mathrm{V}}$$

Now that the derivative has been found, we may plug in values:

$$\frac{di_D}{dv_D}\Big|_{v_D=0.70\,\mathrm{V}} = \frac{1}{26\,\mathrm{mV}}(0.010\,\mathrm{pA})e^{0.70\,\mathrm{V}/26\,\mathrm{mV}} \approx 189.5\,\mathrm{m\Omega}^{-1}$$

We now take the inverse, (1/x), to get the small-signal resistance value.

$$R_{\rm b} = \frac{1}{\frac{di_D}{dv_D}} \bigg|_{v_D = 0.70 \,\mathrm{V}} \approx \frac{1}{189.5 \,\Omega^{-1}} \approx 5.28 \,\Omega$$

b) In the frequency-domain, we use phasors for voltages and currents, and impedances for resistors, capacitors, and inductors.

The phasor transform is captured by the following equation:

 $P[A\cos(\omega t + \phi)] = Ae^{j\phi} \equiv A \angle \phi$ 

We apply this equation to  $v_s$  and  $i_s$  using the same units in the frequencydomain as in the time-domain. The circuit diagram, below, shows the values.

The impedances are calculated with the following formulas:

$$z_R = R$$
  $z_L = j\omega L$   $z_C = \frac{1}{j\omega C} = \frac{-j}{\omega C}$ 

The value of  $\omega = 800$  r/s is found in  $v_{in}(t)$ . Frequency domain circuit values are shown on the circuit diagram below. We may save some effort by noting that doubling the value of *L* increases the impedance by a factor of two, whereas doubling the value of *C* decreases the impedance by a factor of two.

